MetaGrad: Multiple Learning Rates in Online Learning

Tim van Erven



Joint work with: Wouter Koolen, Peter Grünwald

Optimization and Learning Workshop Toulouse, September 11, 2018

Example: Sequential Prediction for Football Games



Precursor to modern football in China Han Dynasty (206 BC – 220 AD)

- Before every match t in the English Premier League, my PhD student Dirk van der Hoeven wants to predict the goal difference Y_t
- Given feature vector $X_t \in \mathbb{R}^d$, he may predict $\hat{Y}_t = w_t^\intercal X_t$ with a linear model
- After the match: observe Y_t
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Goal: Predict almost as well as the best possible parameters u:

$$\mathsf{Regret}_T^{oldsymbol{u}} = \sum_{t=1}^T \ell_t(oldsymbol{w}_t) - \sum_{t=1}^T \ell_t(oldsymbol{u})$$

Online Convex Optimization

- 1: **for** t = 1, 2, ..., T **do**
- 2: Learner estimates w_t from convex $\mathcal{U} \subset \mathbb{R}^d$
- 3: Nature reveals convex loss function $\ell_t:\mathcal{U}\to\mathbb{R}$
- 4: Learner incurs loss $\ell_t({m w}_t)$
- 5: end for

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Viewed as a zero-sum game against Nature:

$$V = \min_{\boldsymbol{w}_1} \max_{\ell_1} \min_{\boldsymbol{w}_2} \max_{\ell_2} \cdots \min_{\boldsymbol{w}_T} \max_{\ell_T} \max_{\boldsymbol{u} \in \mathcal{U}} \underbrace{\sum_{t=1}^T \ell_t(\boldsymbol{w}_t) - \sum_{t=1}^T \ell_t(\boldsymbol{u})}_{\mathsf{Regret}_T^{\boldsymbol{u}}}$$

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Methods: Efficient computations using only gradient $g_t = \nabla \, \ell_t(w_t)$

$$egin{aligned} w_{t+1} &= w_t - \eta_t g_t \ w_{t+1} &= w_t - \eta \Sigma_{t+1} g_t \end{aligned} \qquad ext{(online gradient descent)}$$

where
$$\Sigma_{t+1} = (\epsilon I + 2\eta^2 \sum_{s=1}^t g_s g_s^{\mathsf{T}})^{-1}$$
.

The Standard Picture

Minimax rates based on curvature (bounded domain and gradients) [Hazan, 2016]:

Convex ℓ_t	\sqrt{T}	OGD with $\eta_t \propto rac{1}{\sqrt{t}}$
Strongly convex ℓ_t	In T	OGD with $\eta_t \propto rac{1}{t}$
Exp-concave ℓ_t	d In T	ONS with $\eta \propto 1$

- **Strongly convex:** second derivative at least $\alpha > 0$, implies exp-concave
- **Exp-concave:** $e^{-\alpha \ell_t}$ concave Satisfied by log loss, logistic loss, squared loss, but not hinge loss

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Limitations:

- ▶ Different method in each case. (Requires sophisticated users.)
- ▶ Theoretical tuning of η_t very conservative
- What if curvature varies between rounds?
- ▶ In many applications data are **stochastic** (i.i.d.) Should be easier than worst case. . .

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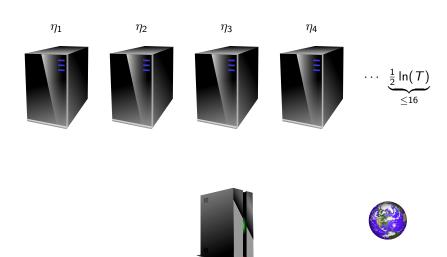
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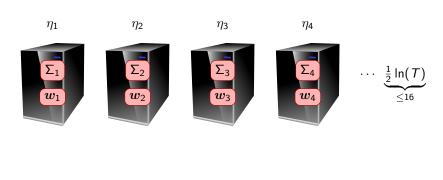
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Need Adaptive Methods!

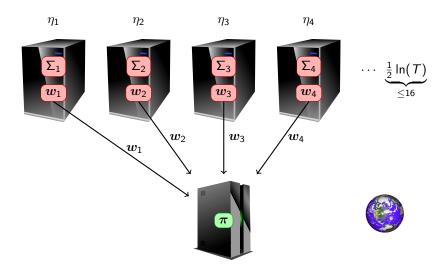
▶ Difficulty: All existing methods learn η at too slow rate [HP2005] so overhead of learning best η ruins potential benefits

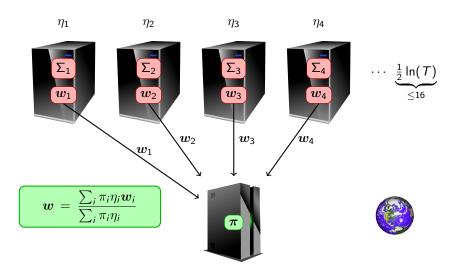


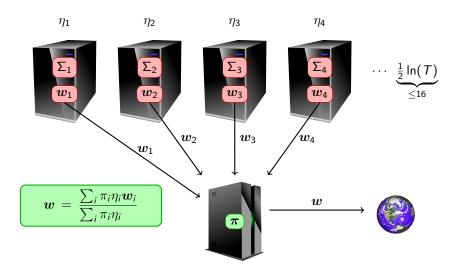


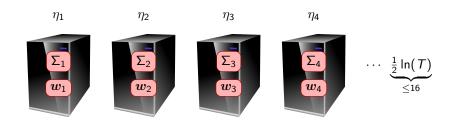




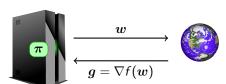


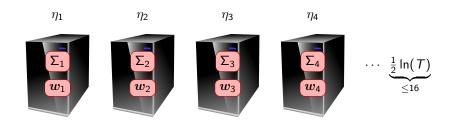




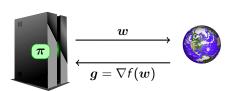


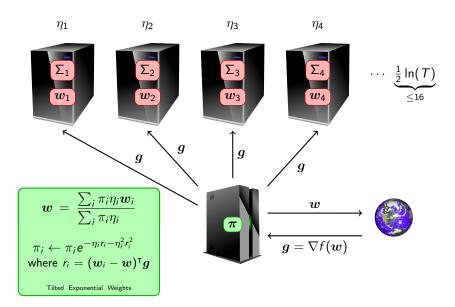
$$\boldsymbol{w} = \frac{\sum_{i} \pi_{i} \eta_{i} \boldsymbol{w}_{i}}{\sum_{i} \pi_{i} \eta_{i}}$$





$$m{w} = rac{\sum_i \pi_i \eta_i m{w}_i}{\sum_i \pi_i \eta_i}$$
 $m{\pi}_i \leftarrow m{\pi}_i e^{-\eta_i r_i - \eta_i^2 r_i^2}$ where $m{r}_i = (m{w}_i - m{w})^{\mathsf{T}} m{g}$





MetaGrad: Multiple Eta G $\Sigma_i \leftarrow (\Sigma_i^{-1} + 2\eta_i^2 g g^{\mathsf{T}})^{-1}$ $\boldsymbol{w}_i \leftarrow \boldsymbol{w}_i - \eta_i \boldsymbol{\Sigma}_i \boldsymbol{g} (1 + 2\eta_i r_i)$ ≈ Quasi Newton update η_1 η_2 η_3 Σ_1 Σ_2 Σ_4 w_1 w_2 w_3 w_4 <16 $\boldsymbol{w} = \frac{\sum_{i} \pi_{i} \eta_{i} \boldsymbol{w}_{i}}{\sum_{i} \pi_{i} \eta_{i}}$ \boldsymbol{w} π $\pi_i \leftarrow \pi_i e^{-\eta_i r_i - \eta_i^2 r_i^2}$ $g = \nabla f(w)$ where $r_i = (w_i - w)^{\mathsf{T}} g$ Tilted Exponential Weights

MetaGrad: Provable Adaptive Fast Rates

Theorem (Van Erven, Koolen, 2016)

MetaGrad's $Regret_T^u$ is bounded by

$$\mathsf{Regret}_T^{m{u}} \leq \sum_{t=1}^T (m{w}_t - m{u})^\mathsf{T} m{g}_t \preccurlyeq egin{cases} \sqrt{T \ln \ln T} \ \sqrt{m{V}_T^{m{u}} d \ln T} + d \ln T \end{cases}$$

where

$$rac{oldsymbol{V_T^u}}{oldsymbol{V_T^u}} = \sum_{t=1}^T ((u-w_t)^\intercal g_t)^2$$

- lacksquare By convexity, $\ell_t(oldsymbol{w}_t) \ell_t(oldsymbol{u}) \leq (oldsymbol{w}_t oldsymbol{u})^\intercal oldsymbol{g}_t.$
- ▶ Optimal learning rate η depends on V_T^u , but u unknown! Crucial to learn best learning rate from data!

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Consequences

1. Non-stochastic adaptation:

T In In T
d In T
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1. Non-stochastic adaptation:

Convex ℓ_t	$\sqrt{T \ln \ln T}$
Exp-concave ℓ_t	d In T
Fixed convex $\ell_t = \ell$	d In T

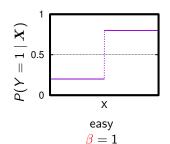
2. Stochastic without curvature

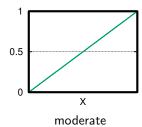
Suppose ℓ_t i.i.d. with stochastic optimum $u^* = \arg\min_{u \in \mathcal{U}} \mathbb{E}_{\ell}[\ell(u)]$. Then expected regret $\mathbb{E}[\mathsf{Regret}_T^{u^*}]$:

Absolute loss* $\ell_t(w) = w - X_t $	In T
Hinge loss $\max\{0, 1 - Y_t \langle oldsymbol{w}, oldsymbol{X}_t angle\}$	d In T
(B,β) -Bernstein	$(Bd \ln T)^{1/(2-\beta)} T^{(1-\beta)/(2-\beta)}$

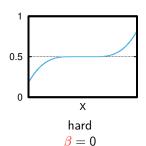
*Conditions apply

Related Work: Adaptivity to Stochastic Data in Batch Classification [Tsybakov, 2004]

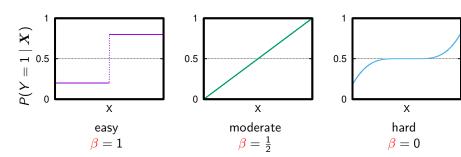




 $\beta = \frac{1}{2}$



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Definition $((B, \beta)$ -Bernstein Condition)

Losses are i.i.d. and

$$\mathbb{E}\left(\ell(oldsymbol{w}) - \ell(oldsymbol{u}^*)
ight)^2 \leq Big(\,\mathbb{E}\left[\ell(oldsymbol{w}) - \ell(oldsymbol{u}^*)
ight]ig)^{oldsymbol{eta}} \qquad ext{for all } oldsymbol{w},$$

where $u^* = \arg\min_{u} \mathbb{E}[\ell(u)]$ minimizes the expected loss.

Suppose ℓ_t i.i.d. with stochastic optimum $u^* = \arg\min_{u \in \mathcal{U}} \mathbb{E}[\ell(u)]$.

Standard Bernstein condition:

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Replace by weaker linearized version:

- Apply with $\tilde{\ell}(u) = \langle u, \nabla \ell(w) \rangle$ instead of $\ell!$
- lacksquare By convexity, $\ell(oldsymbol{w}) \ell(oldsymbol{u}^*) \leq ilde{\ell}(oldsymbol{w}) ilde{\ell}(oldsymbol{u}^*).$

$$\mathbb{E}\left((\boldsymbol{w}-\boldsymbol{u}^*)^\intercal \nabla \ell(\boldsymbol{w})\right)^2 \leq B\big(\,\mathbb{E}\left[(\boldsymbol{w}-\boldsymbol{u}^*)^\intercal \nabla \ell(\boldsymbol{w})\right]\big)^\beta \quad \text{for all } \boldsymbol{w} \in \mathcal{U}.$$

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Hinge loss (domain, gradients bounded by 1): $\beta = 1$, $B = \frac{2\lambda_{\max}(\mathbb{E}[XX^{\intercal}])}{\|\mathbb{E}[YX]\|}$

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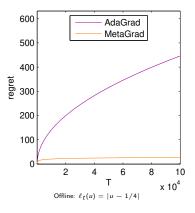
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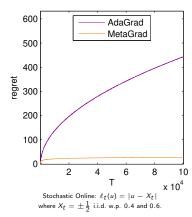
Theorem (Koolen, Grünwald, Van Erven, 2016)

$$\mathbb{E}[\mathsf{Regret}_T^{\boldsymbol{u}^*}] \preccurlyeq (Bd \ln T)^{1/(2-\beta)} \, T^{(1-\beta)/(2-\beta)}$$

$$\mathsf{Regret}_T^{\boldsymbol{u}^*} \preccurlyeq (Bd \ln T - \ln \delta)^{1/(2-\beta)} \, T^{(1-\beta)/(2-\beta)} \quad \textit{w.p.} \ge 1 - \delta$$

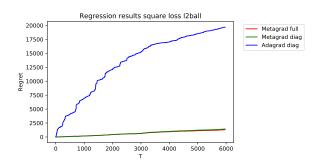
MetaGrad Simulation Experiments





- ▶ MetaGrad: $O(\ln T)$ regret, AdaGrad: $O(\sqrt{T})$, match bounds
- ▶ Functions neither strongly convex nor smooth
- ► Caveat: comparison more complicated for higher dimensions, unless we run a separate copy of MetaGrad per dimension, like the diagonal version of AdaGrad runs GD per dimension

MetaGrad Football Experiments





Dirk van der Hoeven (my PhD student)



Raphaël Deswarte (visiting PhD student)

- Predict difference in goals in 6000 football games in English Premier League (Aug 2000–May 2017).
- Square loss on Euclidean ball
- ▶ 37 features: running average of goals, shots on goal, shots over m = 1, ..., 10 previous games; multiple ELO-like models; intercept.

Second-order surrogate loss for each η of interest (from a grid):

$$\ell_t^{\eta}(\boldsymbol{u}) = \eta(\boldsymbol{u} - \boldsymbol{w}_t)^{\intercal} \boldsymbol{g}_t + \eta^2 (\boldsymbol{u} - \boldsymbol{w}_t)^{\intercal} \boldsymbol{g}_t \boldsymbol{g}_t^{\intercal} (\boldsymbol{u} - \boldsymbol{w}_t)$$

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One Slave algorithm per η produces $oldsymbol{w}_t^{\eta}$ such that

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$$\underbrace{\sum_{t=1}^{T} \ell_t^{\eta}(w_t) - \sum_{t=1}^{T} \ell_t^{\eta}(w_t^{\eta})}_{-0} \leq R_{\mathsf{master}}(\eta) \qquad \forall \eta$$

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Together:
$$-\sum_{t=1}^{T} \ell_t^{\eta}(u) \le R_{\mathsf{slave}}^{u}(\eta) + R_{\mathsf{master}}(\eta) \quad \forall \eta$$

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Together:
$$-\sum_{t=1}^{T} \ell_t^{\eta}(u) \le R_{\text{slave}}^{u}(\eta) + R_{\text{master}}(\eta) \quad \forall \eta$$

$$\sum_{t=1}^T (w_t - u)^\intercal g_t \leq \frac{O(d \ln T) + O(\ln \ln T)}{\eta} + \eta V_T^{\boldsymbol{u}} \Rightarrow O\left(\sqrt{V_T^{\boldsymbol{u}} d \ln T}\right)$$

MetaGrad Master

Goal: aggregate slave predictions $oldsymbol{w}_t^{\eta}$ for all η in

exponentially spaced grid $\frac{2^{-0}}{5DG}, \frac{2^{-1}}{5DG}, \dots, \frac{2^{-\lceil \frac{1}{2} \log_2 T \rceil}}{5DG}$

Difficulty: master's predictions must be good w.r.t. different loss

functions ℓ^{η}_t for all η simultaneously

Compute **exponential weights** with performance of each η measured by its own surrogate loss:

$$\pi_t(\eta) = \frac{\pi_1(\eta)e^{-\sum_{s < t} \ell_s^{\eta}(\boldsymbol{w}_s^{\eta})}}{Z}$$

Then predict with **tilted** exponentially weighted average:

$$oldsymbol{w}_t = rac{\sum_{\eta} \pi_t(\eta) rac{\eta}{\eta} oldsymbol{w}_t^{\eta}}{\sum_{\eta} \pi_t(\eta) rac{\eta}{\eta}}$$

MetaGrad Master Analysis

Potential
$$\Phi_{\mathcal{T}} = \sum_{\eta} \pi_1(\eta) e^{-\sum_{t=1}^{\mathcal{T}} \ell_t^{\eta}(\boldsymbol{w}_t^{\eta})}$$

Proof outline:

$$\begin{split} \Phi_{\mathcal{T}} &\leq \Phi_{\mathcal{T}-1} \leq \dots \leq \Phi_0 = 1 \\ &\pi_1(\eta) e^{-\sum_{t=1}^T \ell_t^{\eta}(\boldsymbol{w}_t^{\eta})} \leq 1 \qquad \forall \eta \\ &\sum_{t=1}^T \ell_t^{\eta}(\boldsymbol{w}_t) - \sum_{t=1}^T \ell_t^{\eta}(\boldsymbol{w}_t^{\eta}) \leq -\ln \pi_1(\eta) \end{split}$$

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Grid has $\lceil \frac{1}{2} \log_2 T \rceil + 1$ learning rates, so for heavy-tailed prior:

$$-\ln \pi_1(\eta) = O(\ln \ln T)$$

MetaGrad Master Analysis: Decreasing Potential

Surrogate loss $\ell_t^{\eta}(u) = \eta(u - w_t)^{\mathsf{T}} g_t + \eta^2 (u - w_t)^{\mathsf{T}} g_t g_t^{\mathsf{T}} (u - w_t)$ is exp-concave, even if f_t is not.

Upper bound by tangent at $u = w_t$:

$$e^{-\ell_t^{\eta}(\boldsymbol{u})} \leq 1 + \eta(\boldsymbol{w}_t - \boldsymbol{u})^{\intercal} \boldsymbol{g}_t$$

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Choose master's weights to ensure decreasing potential:

$$\begin{split} \Phi_T - \Phi_{T-1} &= \sum_{\eta} \pi_1(\eta) e^{-\sum_{t < T} \ell_t^{\eta}(\boldsymbol{w}_t^{\eta})} \left(e^{-\ell_T^{\eta}(\boldsymbol{w}_T^{\eta})} - 1 \right) \\ &\leq \sum_{\eta} \pi_1(\eta) e^{-\sum_{t < T} \ell_t^{\eta}(\boldsymbol{w}_t^{\eta})} \eta(\boldsymbol{w}_T - \boldsymbol{w}_T^{\eta})^{\mathsf{T}} \boldsymbol{g}_T \\ &= 0 \quad \text{ for any } \boldsymbol{g}_T \end{split}$$

Summary

MetaGrad:

- Consider multiple learning rates η simultaneously
- Learn η from the data, at very fast rate (pay only $\ln \ln T$)
- New adaptive variance bound

Variance bound implies fast rates in:

- ▶ all known cases: exp-concave, strong convex
- new cases with stochastic data, characterized by online version of Bernstein condition

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