Robust Online Convex Optimization in the Presence of Outliers

Tim van Erven



COLT 2021



Sarah Sachs



Wouter Koolen



Wojciech Kotłowski

Recruiting: Postdoc position in my group available 2022

Extreme Outliers Can Break Learning



X1

Reasons for outliers:

- Naturally heavy-tailed data
- A small subset of malicious users trying to corrupt data stream
- Glitches in cheap sensors

Heavily studied:

- In statistics [Tukey, 1959, Huber, 1964], stochastic optimization, etc.
- But not yet in Online Convex Optimization

Formalizing Robust OCO

Standard OCO setting:

Given convex domain $\mathcal{W} \subset \mathbb{R}^d$ with diameter $(\mathcal{W}) \leq D$

- 1: for t = 1, 2, ..., T do
- 2: Predict w_t in \mathcal{W}
- 3: Observe convex loss function $f_t:\mathcal{W} o\mathbb{R}$ with gradient $m{g}_t=
 abla f_t(m{w}_t)$
- 4: end for

Robust regret:
$$R_T(u, S) = \sum_{t \in S} (f_t(w_t) - f_t(u))$$

Challenges:

- ▶ Inliers $S \subset \{1, ..., T\}$ unknown (chosen by adversary)
- Bounds cannot depend on outliers at all, but must scale with

$$G(\mathcal{S}) = \max_{t \in \mathcal{S}} \|\boldsymbol{g}_t\|.$$

Robustifying Any OCO Algorithm

- 1. Any OCO ALG with regret bound $B_T(G)$ if gradients have length at most G
- 2. Top-k Filter: simple strategy to filter out large gradients

Theorem (At most k outliers)

On linear losses, ALG + Top-k Filter achieves

$$R_T(u, S) \leq \underbrace{B_T(2G(S))}_{k} + 4DG(S)(k+1)$$
 for any $S: T - |S| \leq k$.

Feed ALG gradients $\leq 2G(S)$

Robustifying Any OCO Algorithm

- 1. Any OCO ALG with regret bound $B_T(G)$ if gradients have length at most G
- 2. Top-k Filter: simple strategy to filter out large gradients

Theorem (At most k outliers)

On linear losses, **ALG** + **Top**-k **Filter** achieves

$$R_T(u, S) \leq B_T(2G(S)) + 4DG(S)(k+1)$$
 for any $S: T - |S| \leq k$.

price of robustness = O(G(S)k)

Robustifying Any OCO Algorithm

- 1. Any OCO ALG with regret bound $B_T(G)$ if gradients have length at most G
- 2. Top-*k* Filter: simple strategy to filter out large gradients

Theorem (At most k outliers)

On linear losses, ALG + Top-k Filter achieves

 $R_T(u,\mathcal{S}) \leq B_Tig(2\mathcal{G}(\mathcal{S})ig) + 4D\mathcal{G}(\mathcal{S})(k+1) \qquad ext{for any } \mathcal{S}: \, T - |\mathcal{S}| \leq k.$

Losses	Minimax Robust Regret
General convex	$O(\sqrt{T}+k)$
${\sf General} \ {\sf convex} + {\sf i.i.d.}$	н
Strongly convex	$O(\ln(T)+k)$

Efficient Filtering Approach

Top-*k* **Filter:**

- ▶ Maintain list L_t of k + 1 largest gradient lengths seen so far
- Filter round if $||g_t|| > 2 \min \mathcal{L}_t$; otherwise pass to ALG

Main Ideas:

- 1. Never pass ALG gradients > 2G(S):
 - $\blacktriangleright \mathcal{L}_t$ contains at least 1 inlier, because at most k outliers
 - Hence min $\mathcal{L}_t \leq G(\mathcal{S})$
- 2. Overhead for filtering is O(k)
 - Every filtered round is also added to \mathcal{L}_t
 - Therefore min \mathcal{L}_t (at least) doubles every k + 1 filtered rounds
 - Hence last k + 1 filtered rounds dominate

Application: Robustified Online-to-Batch

Outlier distribution

Huber ϵ -contamination model:

$$P_{\epsilon} = (1 - \epsilon)P + \epsilon Q$$

Distribution of interest

•
$$f_t(w) = f(w, \xi)$$
 where $\xi \sim P_{\epsilon}$

▶ Inlier risk:
$$\operatorname{Risk}_{P}(w) = \mathbb{E}_{\xi \sim P}[f(w, \xi)]$$

Application: Robustified Online-to-Batch

Outlier distribution

Huber ϵ -contamination model:

$$P_{\epsilon} = (1 - \epsilon)P + \epsilon Q$$

Distribution of interest

•
$$f_t(w) = f(w, \xi)$$
 where $\xi \sim P_e$

▶ Inlier risk:
$$\mathsf{Risk}_P(w) = \mathbb{E}_{\xi \sim P}[f(w, \xi)]$$

Corollary (Optimal Rate via Robust Online-to-Batch)

Suppose $\|\nabla f(w,\xi)\| \leq G$ a.s. when $\xi \sim P$ is an inlier. Then iterate average $\bar{w}_T = \frac{1}{T} \sum_{t=1}^T w_t$ of OGD + Top-k Filter achieves

$$\mathsf{Risk}_{P}(\bar{\boldsymbol{w}}_{T}) - \min_{\boldsymbol{u}\in\mathcal{W}}\mathsf{Risk}_{P}(\boldsymbol{u}) = O\left(DG\epsilon + DG\sqrt{\frac{\ln(1/\delta)}{T}}\right)$$

with P_{ϵ} -probability at least $1 - \delta$, for some k tuned for ϵ, δ, T .

Quantile Outliers

Which extra assumptions allow sublinear dependence on number of outliers *k*?

||g_t|| ≤ L||X_t|| for i.i.d. X_t (e.g. hinge loss, logistic loss)
 Inliers S_p are rounds s.t. ||X_t|| less than p-quantile X_p

Quantile Outliers

Which extra assumptions allow sublinear dependence on number of outliers *k*?

 $igstarrow \|m{g}_t\| \leq L \|m{X}_t\|$ for i.i.d. $m{X}_t$ (e.g. hinge loss, logistic loss)

▶ Inliers S_p are rounds s.t. $||X_t||$ less than *p*-quantile X_p

Theorem (Sublinear Outlier Overhead)

Suppose ALG has regret bound $B_T(X)$, concave in T, if non-filtered X_t have length at most X. Then ALG + p-Quantile Filter achieves

$$\mathbb{E}\left[\max_{\boldsymbol{u}\in\mathcal{W}}R_{T}(\boldsymbol{u},\mathcal{S}_{p})\right]\leq B_{pT}(X_{p})+O\left(LDX_{p}\sqrt{p(1-p)T\ln T}+\ln(T)^{2}\right).$$

p-Quantile Filter:

Filter when $||X_t|| \ge \text{lower-confidence bound on } X_p$

Summary

Robust regret: measure regret only on (unknown) inlier rounds

Price of Robustness = Overhead over usual regret rate:

• At most k adversarial outliers: O(k)

▶ *p*-Quantile outliers: $O(\sqrt{p(1-p)T\ln(T)} + \ln(T)^2)$

PS. I am looking for a postdoc, starting anytime in 2022. Please get in touch if you want to come to Amsterdam!