

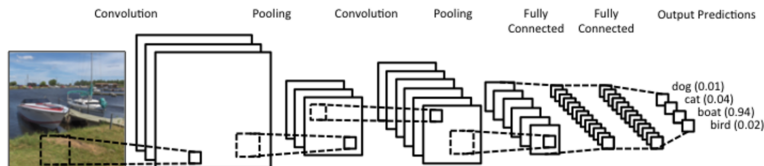
# Dynamic Routing Between Capsules

Sara Sabour, Nicholas Frosst and Geoffrey E. Hinton  
(Google Brain, Toronto)

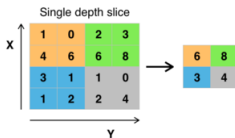
presented by  
William Weimin Yoo  
(Leiden University)

National NIPS Debriefing, 2018

# What is wrong with Convolutional Neural Nets?



1. Does not encode spatial relationships, e.g., orientation, rotations etc.
2. Max pooling looks only at most active neuron, location information is not recorded  $\Rightarrow$  positional invariance





person

0.88



reddish orange color 0.78



light brown color 0.78



starlet 0.66



entertainer 0.66



female 0.60



woman 0.59



young lady (heroine) 0.59



person

0.90



light brown color 0.84



starlet 0.77



entertainer 0.77



female 0.65



woman 0.64



young lady (heroine) 0.64



reddish orange color 0.64



newsreader 0.50



coal black color

0.79



hairpiece (hair) 0.71



dress 0.71



maroon color 0.71



person 0.58



toupee (hairpiece) 0.58



woman 0.56



Earrings 0.55



female 0.50



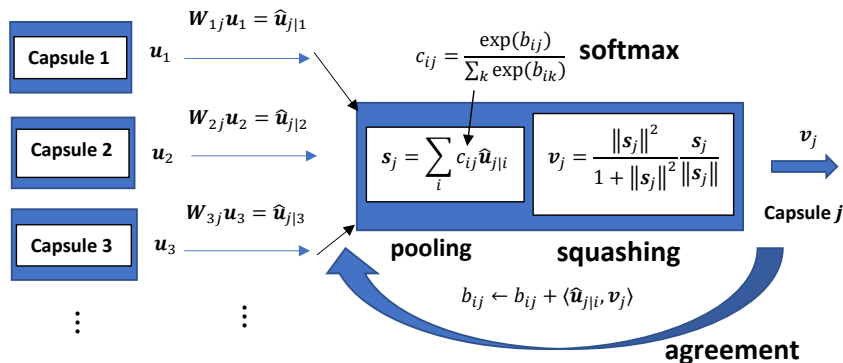
# Capsules and Routing

1. Capsule is a group of neurons encoding properties (instantiation parameters) of entities in an image (e.g., circle, 1)
2. Parameters: existence, pose (position, size, orientation), deformation, hue, texture etc.
3. So unlike CNN (scalars), outputs and inputs are (high-dimensional) vectors
4. Norm of vectors encode probability of existence
5. Draws analogy from computer graphics, points on linear manifold and transformation
6. Max pooling is too crude, how to route vectors of instantiation parameters from one capsule layer to another?

# MNIST

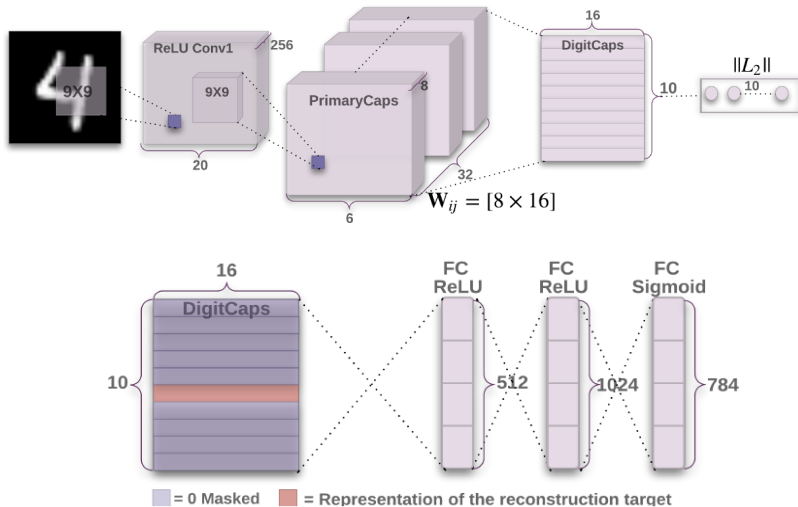


# Dynamic Routing by Agreement



# CapsNet Architecture

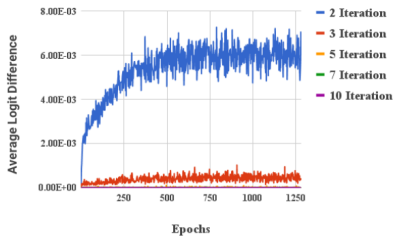
1 Conv. layer + 2 Capsule layers + 3 Fully connected



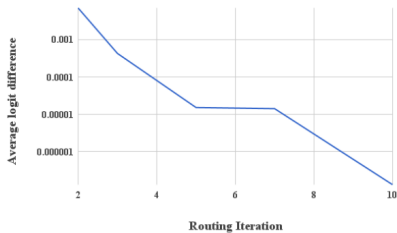
# How many routing iterations?

Average change of  $b_{ij}$  (routing logit) vs. routing iterations:

(a) During training.



(b) Log scale of final differences.



Stabilizes after 500 epochs of training.  
Negligible change ( $1 \times 10^{-5}$ ) by 5 iterations.



# Margin Loss for Digit Existence

$L_k$ : Margin loss for digit capsule  $k$

$\mathbf{v}_k$ : Output from digit capsule  $k$

$$L_k = T_k \max(0, m^+ - \|\mathbf{v}_k\|)^2 + \lambda(1 - T_k) \max(0, \|\mathbf{v}_k\| - m^-)^2$$

$T_k = 1$  iff digit  $k$  present

$m^+ = 0.9$  and  $m^- = 0.1$

$\lambda = 0.5$

▷ Train using backpropagation (Rumelhart, 1986) with Adam optimizer (Kingma and Ba 2014) to minimize  $\sum_{k=1}^{10} L_k$   
Implemented using Tensor Flow (Abadi et al. 2016)













Total loss = Margin loss + 0.0005 × (Reconstruction loss)

# MNIST Reconstructions

$l$ : label

$p$ : prediction

$r$ : target reconstruction

$(l, p, r)$	$(2, 2, 2)$	$(5, 5, 5)$	$(8, 8, 8)$	$(9, 9, 9)$		$(5, 3, 5)$	$(5, 3, 3)$
Input							
Output							



Correct with noise smoothing



Wrong and confused

# MNIST Classification Results


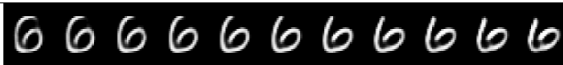

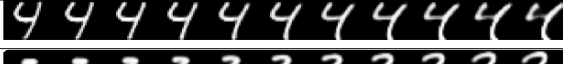


Method	Routing	Reconstruction	MNIST (%)	MultiMNIST (%)
Baseline	-	-	0.39	8.1
CapsNet	1	no	$0.34 \pm 0.032$	-
CapsNet	1	yes	$0.29 \pm 0.011$	7.5
CapsNet	3	no	$0.35 \pm 0.036$	-
CapsNet	3	yes	<b><math>0.25 \pm 0.005</math></b>	<b>5.2</b>

- ▶ Baseline is 3 Conv. layer CNN + 2 FC (dropout) + softmax
- ▶ Designed so that comp. cost  $\approx$  CapsNet
- ▶ Parameters: Baseline 35.4M vs. CapsNet 8.2M

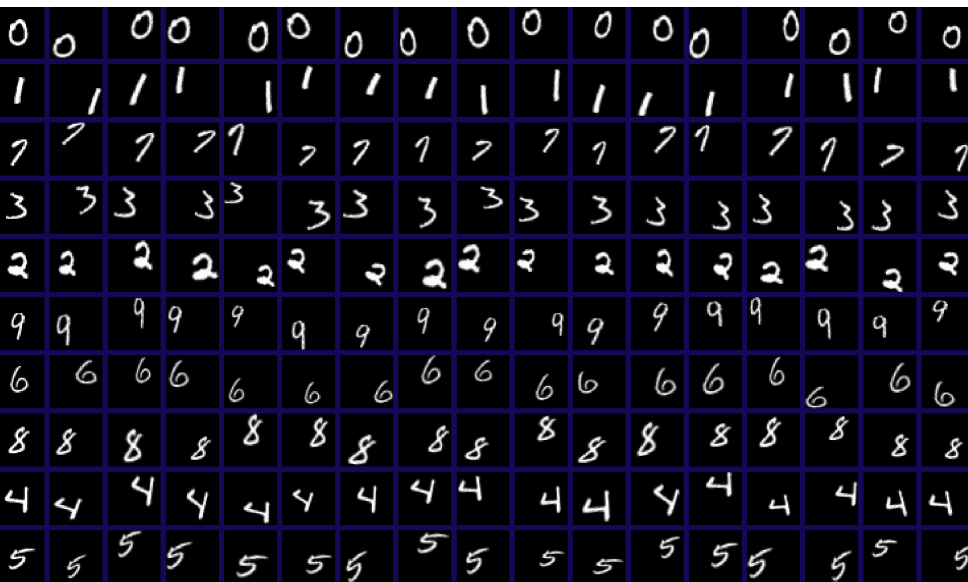
$\Rightarrow$  CapsNet can achieve state-of-art performance with relatively shallow (3) network

# Dimension Perturbations

$d$ th DigitCaps  $(16 \times 1) + [-0.25, -0.2, \dots, 0, \dots, 0.2, 0.25]$   
for  $d = 1, \dots, 6$ :

Scale and thickness	
Localized part	
Stroke thickness	
Localized skew	
Width and translation	
Localized part	

# AffNIST



# Robust to Affine Transformations

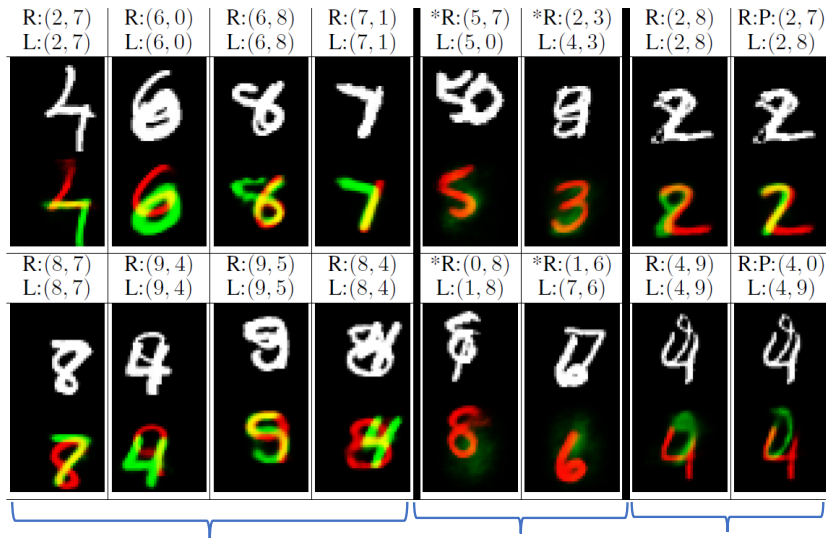
**expanded MNIST**: digits placed randomly on  $40 \times 40$  pixels

**affNIST**: MNIST + random small affine transformation

	<b>expanded MNIST</b>	<b>affNIST</b>
<b>CapsNet</b>	99.23%	79%
<b>CNN</b>	99.22%	66%

Table: Test errors

# MultiMNIST



Correct

Reconstruction  
not from label  
or prediction

Wrong

# MultiMNIST Classification Results

Take learning rate  $10\times$  larger because training dataset is larger

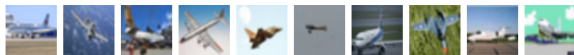
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CapsNet	3	yes	<b><math>0.25 \pm 0.005</math></b>	<b>5.2</b>

- ▶ Baseline CNN: 2Conv. layer+2 FC (ReLU and pooling in between)
- ▶ Parameters: 24.56 M for CNN vs. 11.36 M CapsNet
- ▶ State-of-the-art performance on segmentation



# CIFAR10: $10.6\% \approx \text{CNN}$ (Zeiler and Fergus 2013)

**airplane**



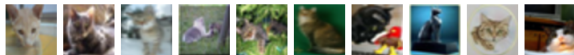
**automobile**



**bird**



**cat**



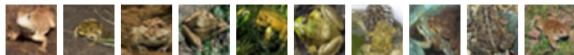
**deer**



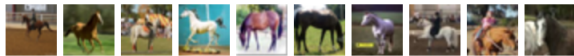
**dog**



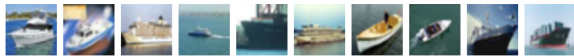
**frog**



**horse**



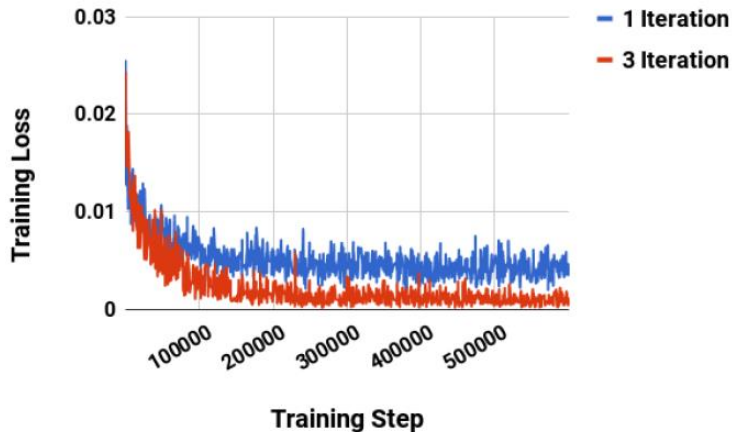
**ship**



**truck**

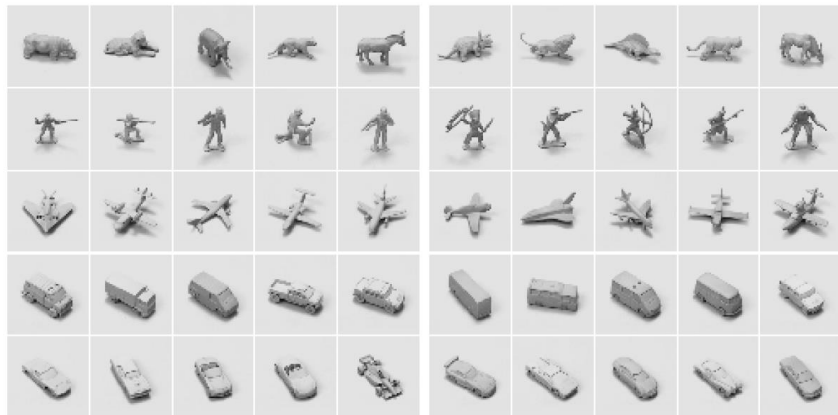


# CIFAR10 Iterations (3 recommended)



# smallNORB

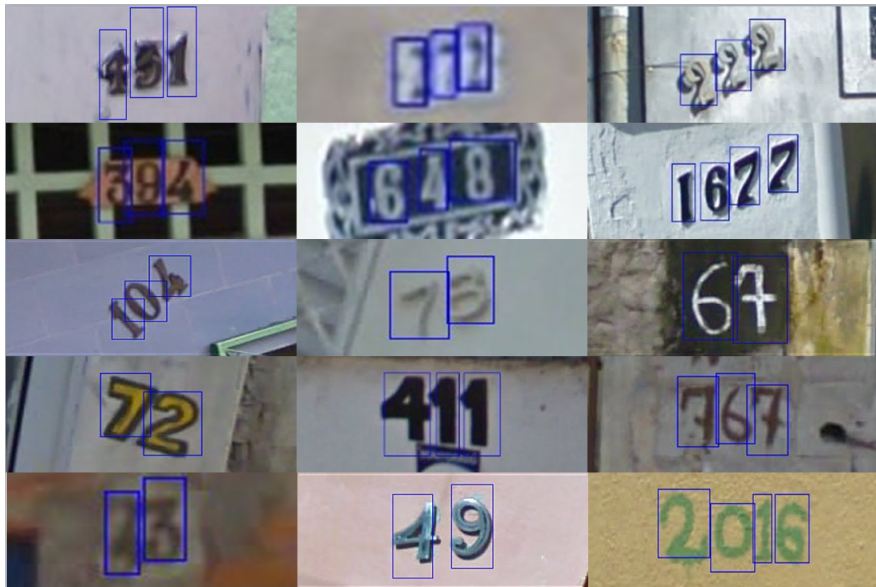
2.7% error  $\approx$  state-of-the-art Cireřan et al. 2011



Training instances

Test instances

SVHN: 4.3% error



Tensor Flow implementation in Sara Sabour's GitHub:  
<https://github.com/Sarasra/models/tree/master/research/capsules>

New (follow-up) paper for ICLR 2018 by the same authors:  
*Matrix Capsules with EM Routing*