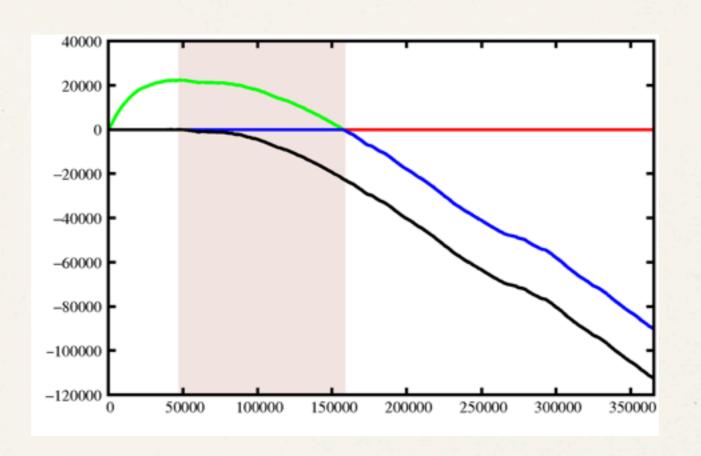
The Catch-up Phenomenon in Bayesian and MDL Model Selection



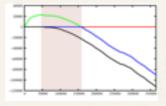
Tim van Erven

www.timvanerven.nl 23 May 2013

Joint work with Peter Grünwald, Steven de Rooij and Wouter Koolen

Outline

- * Bayes Factors and MDL Model Selection
 - Consistent, but suboptimal predictions
- * Explanation: the Catch-up Phenomenon
 - Predictive MDL interpretation of Bayes factors
 - Markov chain example



- * Solution: the Switch Distribution
 - Simulations & Theorems: consistent + optimal predictions
 - Cumulative risk

Two Desirable Properties in Model Selection

- * Suppose $\mathcal{M}_1, \dots, \mathcal{M}_K$ are statistical models (sets of probability distributions: $\mathcal{M}_k = \{p_\theta | \theta \in \Theta_k\}$)
- * Consistency: If some p^* in model \mathcal{M}_{k^*} generates the data, then \mathcal{M}_{k^*} is selected with probability one as the amount of data goes to infinity.
- * Rate of convergence: How fast does an estimator based on the available models converge to the true distribution?

AIC-BIC Dilemma

	Consistent	Optimal rate of convergence
BIC, Bayes, MDL	Yes	No
AIC, LOO Cross-validation	No	Yes

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Bayesian Prediction

* Given model $\mathcal{M}_k = \{p_\theta | \theta \in \Theta_k\}$ with prior w_k and data $x^n = (x_1, \dots, x_n)$, the Bayesian marginal likelihood is

$$\bar{p}_k(x^n) \equiv p(x^n | \mathcal{M}_k) := \int_{\Theta_k} p_{\theta}(x^n) w_k(\theta) d\theta$$

* Given \mathcal{M}_k predict with estimator

$$\bar{p}_k(x_{n+1}|x^n) = \frac{\bar{p}_k(x^{n+1})}{\bar{p}_k(x^n)} = \int_{\Theta_k} p_{\theta}(x_{n+1}|x^n) w_k(\theta|x^n) d\theta$$

Bayes Factors and MDL Model Selection

- * Suppose we have multiple models $\mathcal{M}_1, \mathcal{M}_2, \dots$
- * Bayes factors: Put a prior π on model index k and choose $\hat{k}(x^n)$ to maximize the posterior probability

$$p(\mathcal{M}_k|x^n) := \frac{\bar{p}_k(x^n)\pi(k)}{\sum_{k'} \bar{p}_{k'}(x^n)\pi(k')}$$

* $\hat{k}(x^n)$ is minimizing

$$-\log \bar{p}_k(x^n) - \log \pi(k) \approx -\log \bar{p}_k(x^n)$$

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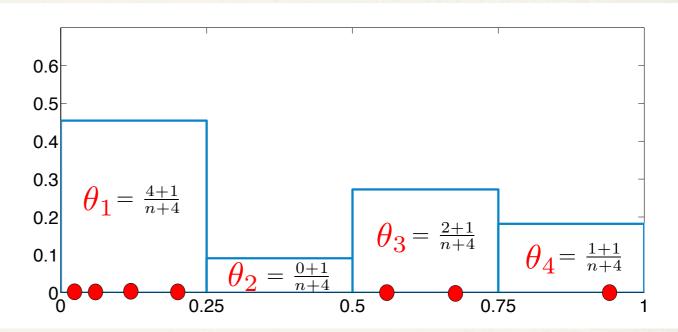
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Minimum Description Length (MDL)

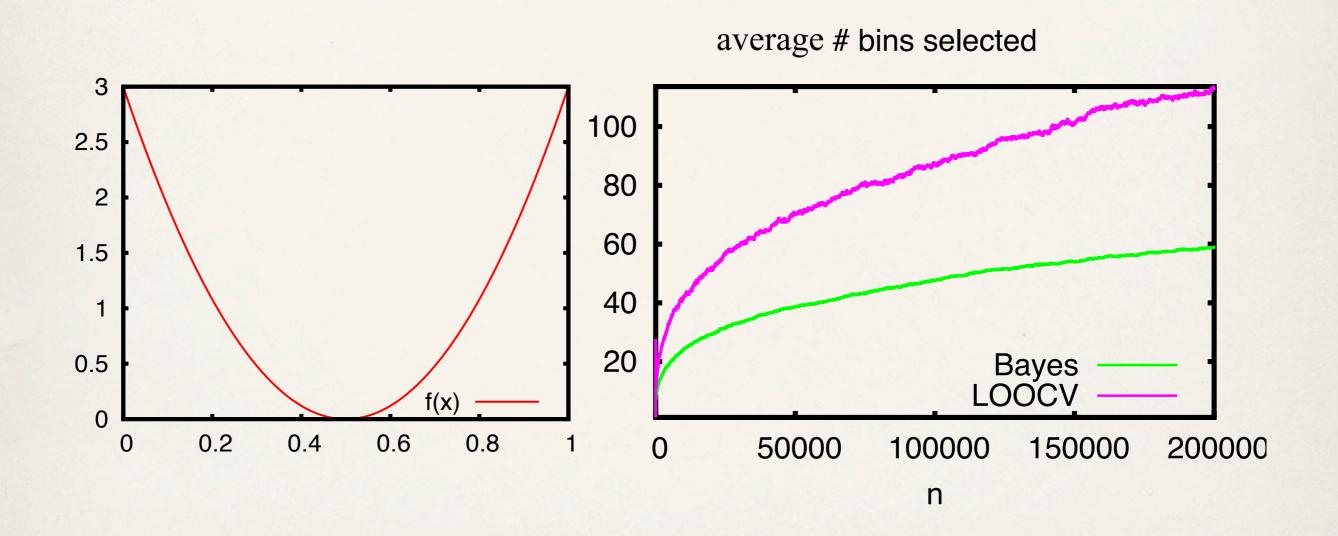
Example: Histogram Density Estimation

$$\mathcal{M}_k = \{ p_\theta | \theta \in \Theta_k \subset \mathbb{R}^k \}$$



- * I.I.D. data in interval [0,1]
- * Given k, estimate density by the estimator in the figure
- * This is equivalent to \bar{p}_k for conjugate Dirichlet(1,...,1) prior
- * How should we choose the number of bins k?
 - * Too few: does not capture enough structure
 - Too many: overfitting (many bins will be empty)
- * [Yu, Speed, '92]: Bayes does not achieve the optimal rate of convergence!

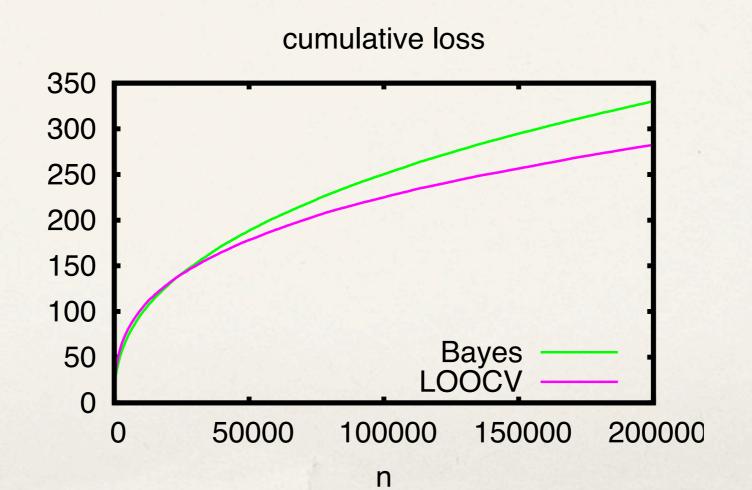
CV Selects More Bins than Bayes



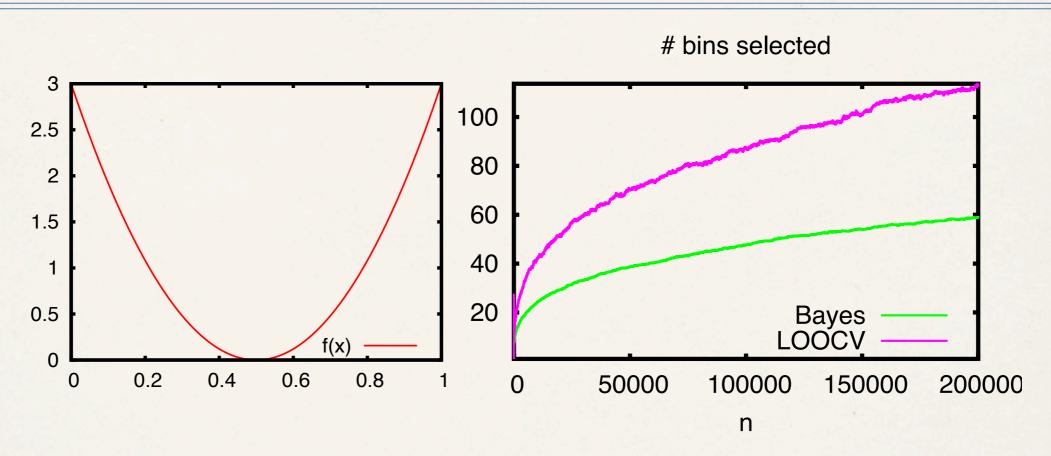
CV Predicts Better than Bayes

Prediction error in log loss at sample size n: $-\log \bar{p}_{\hat{k}(x^n)}(x_{n+1}|x^n)$

cumulative prediction error:
$$\sum_{i=1}^{n} -\log \bar{p}_{\hat{k}(x^{i-1})}(x_i|x^{i-1})$$



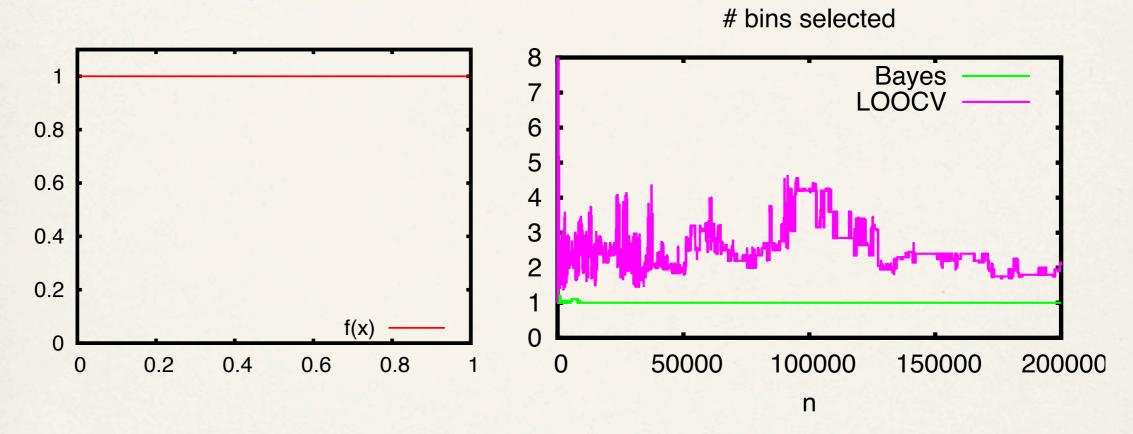
CV Predicts Better than Bayes...



- Density not a histogram, but can be approximated arbitrarily well
- LOO-CV, AIC converge at optimal rate
- * Bayesian model selection selects too few bins (underfits)!

... but CV is Inconsistent!

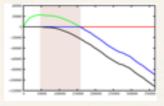
Now suppose data are sampled from the uniform distribution



LOO cross-validation selects 2.5 bins on average: it is inconsistent!

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Logarithmic Loss

If we measure prediction quality by log loss

$$loss(p, x) := -\log p(x)$$

then minus log likelihood = cumulative log loss:

$$-\log p(x_1, \dots, x_n) = \sum_{i=1}^n -\log p(x_i|x^{i-1})$$

where $x^{i-1} = (x_1, \dots, x_{i-1})$

Proof. Take the negative logarithm of the chain rule: $p(x_1, \dots, x_n) = \prod_{i=1}^n p(x_i|x^{i-1})$

The Most Important Slide

Bayes factors and MDL pick the k minimizing

$$-\log \bar{p}_{k}(x_{1},\ldots,x_{n}) = \sum_{i=1}^{n} -\log \bar{p}_{k}(x_{i}|x^{i-1})$$

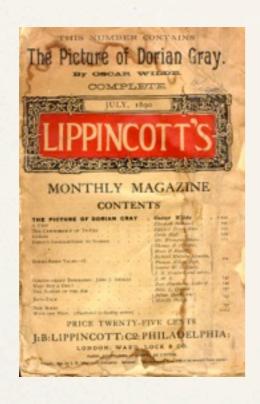
Prediction error for model \mathcal{M}_k at sample size i!

Prequential/predictive MDL interpretation:

select the model \mathcal{M}_k such that, when used as a sequential prediction strategy, \bar{p}_k minimizes cumulative sequential prediction error

[Dawid '84, Rissanen '84]

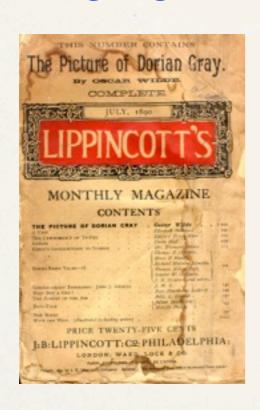
Natural language text: "The Picture of Dorian Gray" by Oscar Wilde



"... But beauty, real beauty, ends where an intellectual expression begins. Intellect is in itself a mode of exaggeration, and destroys the harmony of any face. The moment one sits down to think, one becomes all nose, or all forehead, or something horrid. Look at the successful men in any of the learned professions. How perfectly hideous they are! ..."

Compare the first-order and second-order Markov chain models on the first n characters in the book, with uniform priors on the transition probabilities

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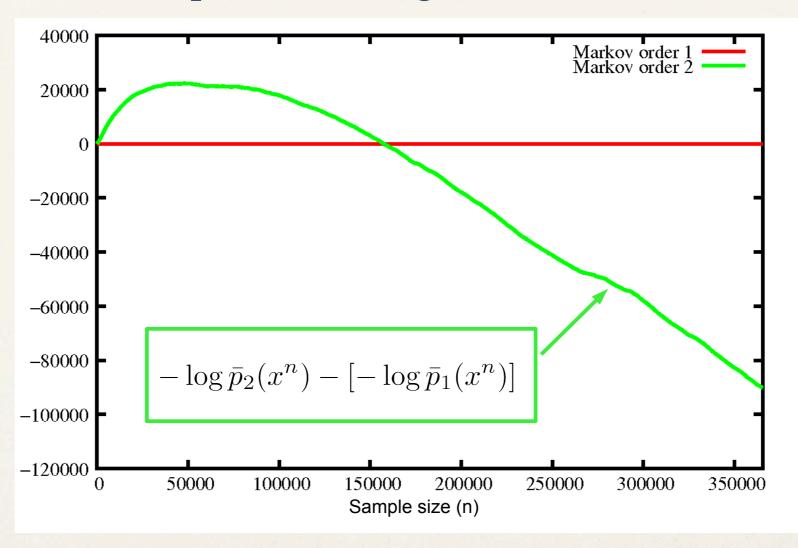
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128x127 parameters

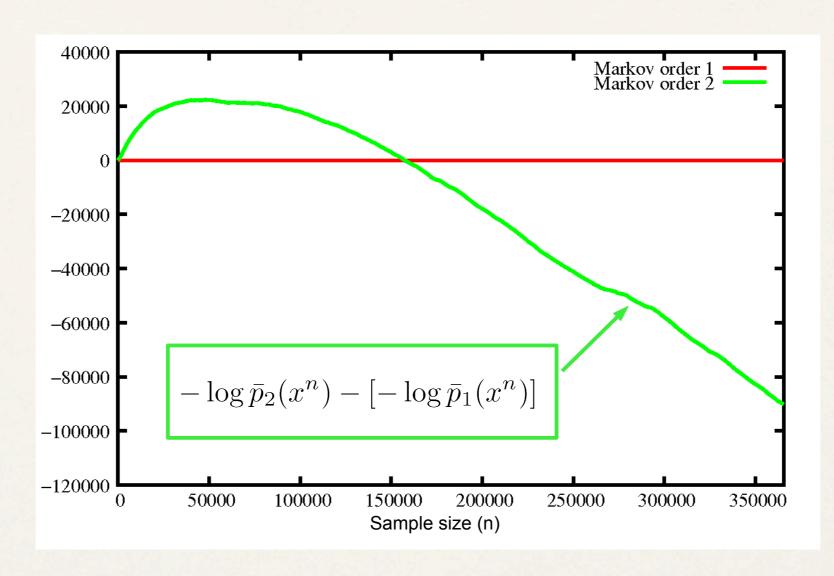
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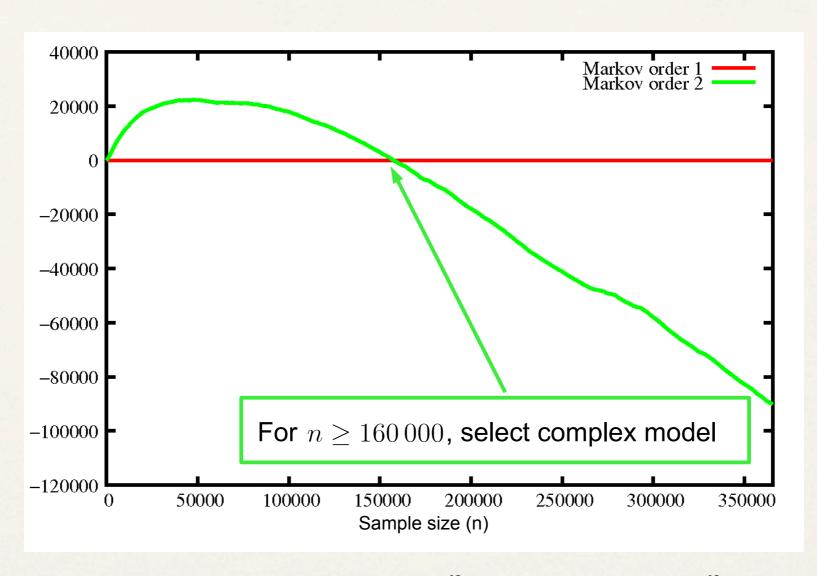
Compare the marginal likelihoods



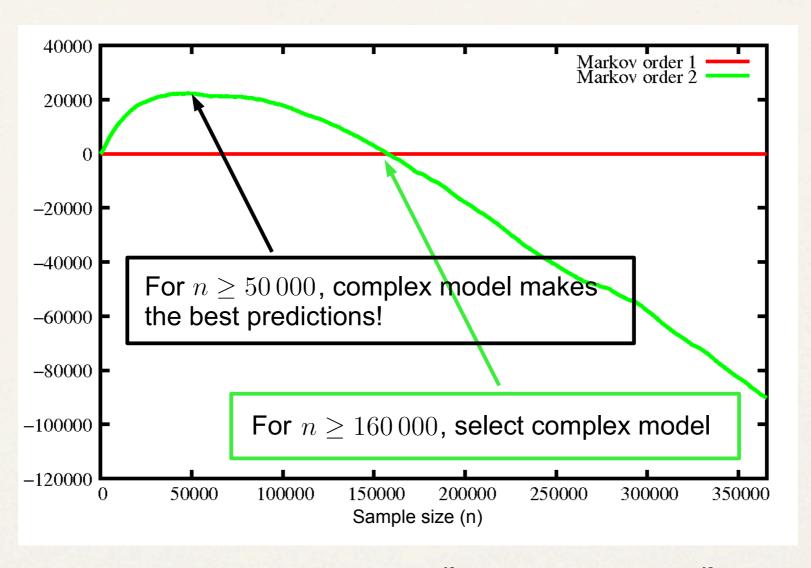
(green line equals the log of the Bayes factor)



$$-\log \bar{p}_2(x^n) - \left[-\log \bar{p}_1(x^n)\right] = \sum_{i=1}^n \log(\bar{p}_2, x_i) - \sum_{i=1}^n \log(\bar{p}_1, x_i)$$



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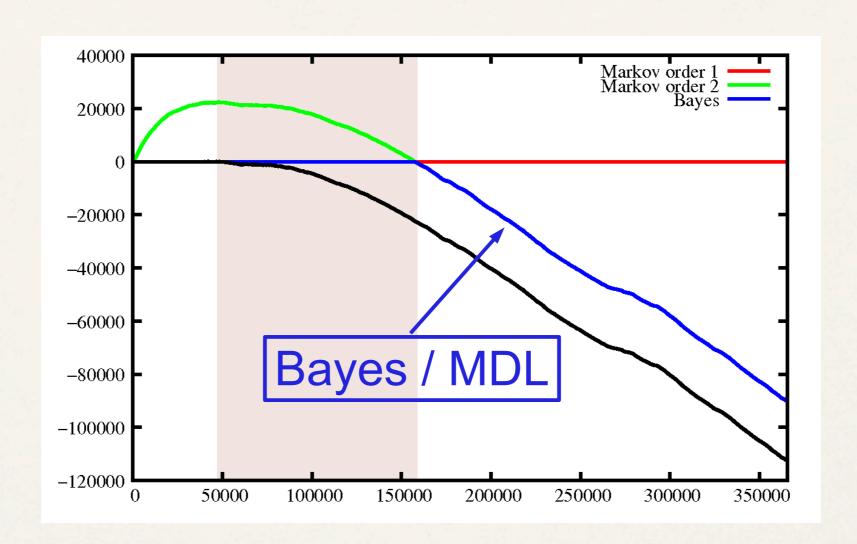
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The Catch-up Phenomenon

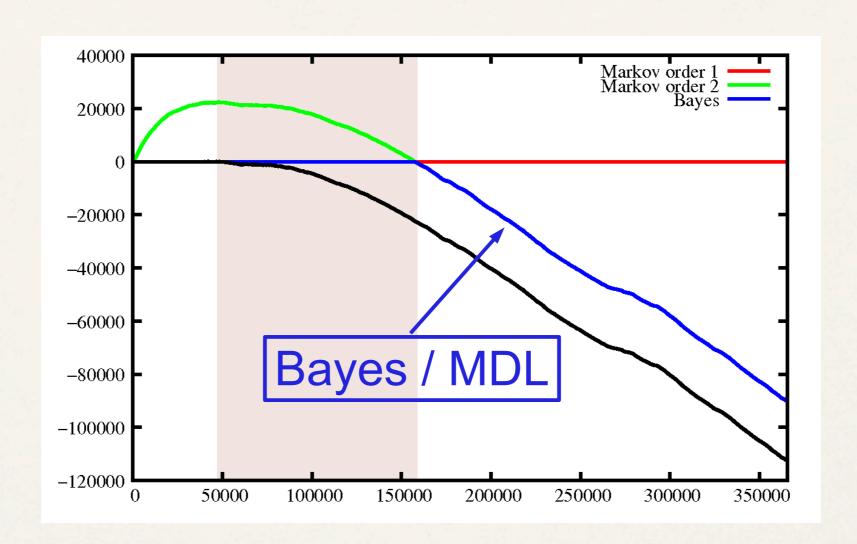
- * Given "simple" model \mathcal{M}_1 and a "complex" model \mathcal{M}_2
- Common phenomenon: for some sample size s
 - * simple model predicts better if $n \le s$
 - complex model predicts better if n > s



- * Catch-up Phenomenon: Bayes/MDL exhibit inertia
 - complex model has to "catch up",
 so we prefer simpler model for a while even after n > s!
- * Remark: Methods similar to Bayes factors (e.g. BIC) will also exhibit the catch-up phenomenon. Bayesian model averaging does not help either!



Can we modify Bayes so as to do as well as the black curve?

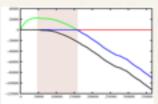


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Almost!

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The Best of Both Worlds

- * Catch-up phenomenon: new explanation for poor predictions of Bayes (and other BIC-like methods)
- We want a model selection/averaging method that, in a wide variety of circumstances,
 - * is provably consistent,
 - * provably achieves optimal convergence rates
- But it has previously been suggested that this is impossible!
 [Yang '05]

The Best of Both Worlds

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- We want a model selection/averaging method that, in a wide variety of circumstances,
 - * is provably consistent,
 - provably achieves optimal convergence rates
- * But it has previously been suggested that this is impossible! [Yang '05]
- * So we have to be careful to avoid impossibility results...

* To avoid the catch-up phenomenon we would like to switch between models at switch-point s:

$$p_{sw}(x^n|s) := \prod_{i=1}^s \bar{p}_1(x_i|x^{i-1}) \times \prod_{i=s+1}^n \bar{p}_2(x_i|x^{i-1})$$

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- * Q. But how do we know when to switch?!
- * A. Switch distribution: do not put a prior π on models, but on when to switch between models:

$$p_{\mathrm{sw}}(x^n) := \sum_{s \ge 0} p_{\mathrm{sw}}(x^n|s)\pi(s)$$

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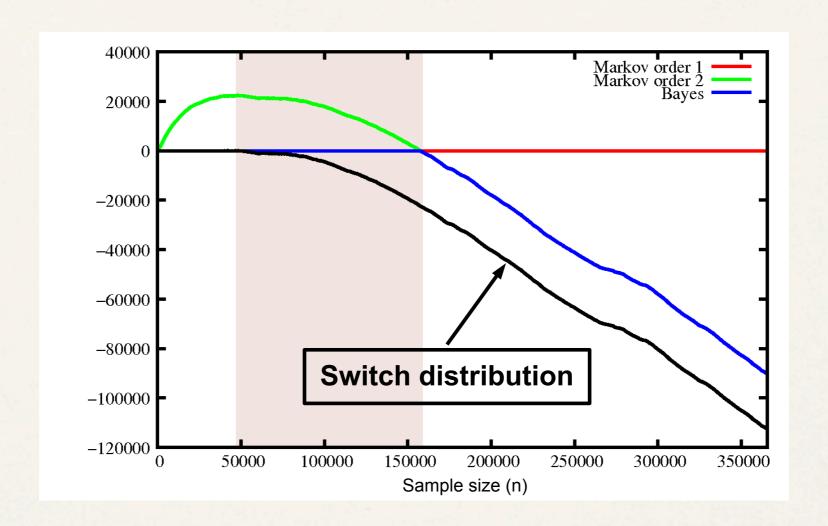
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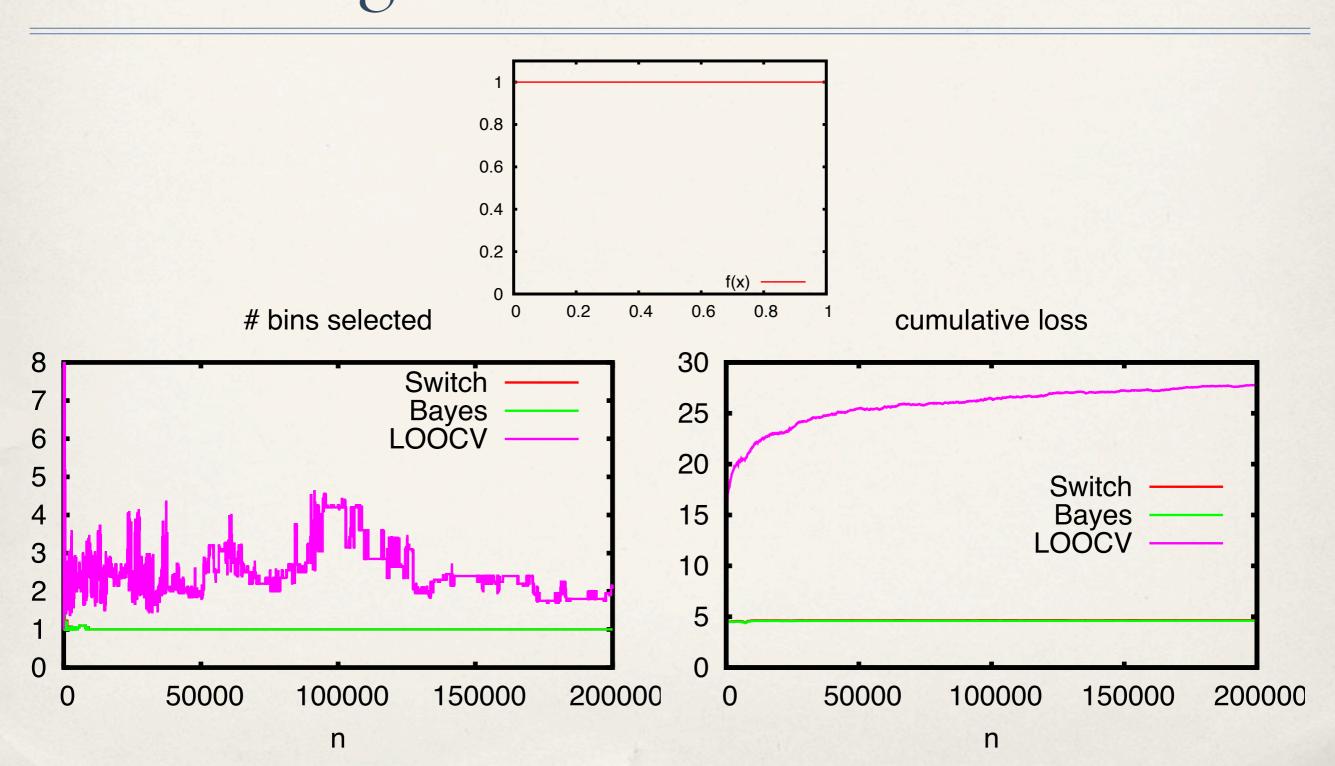
- * Generalizes to an arbitrary (unknown) number of switches between any countable number of models.
- * For many model classes, method is computationally feasible.

Switching Resolves the Catch-up Phenomenon

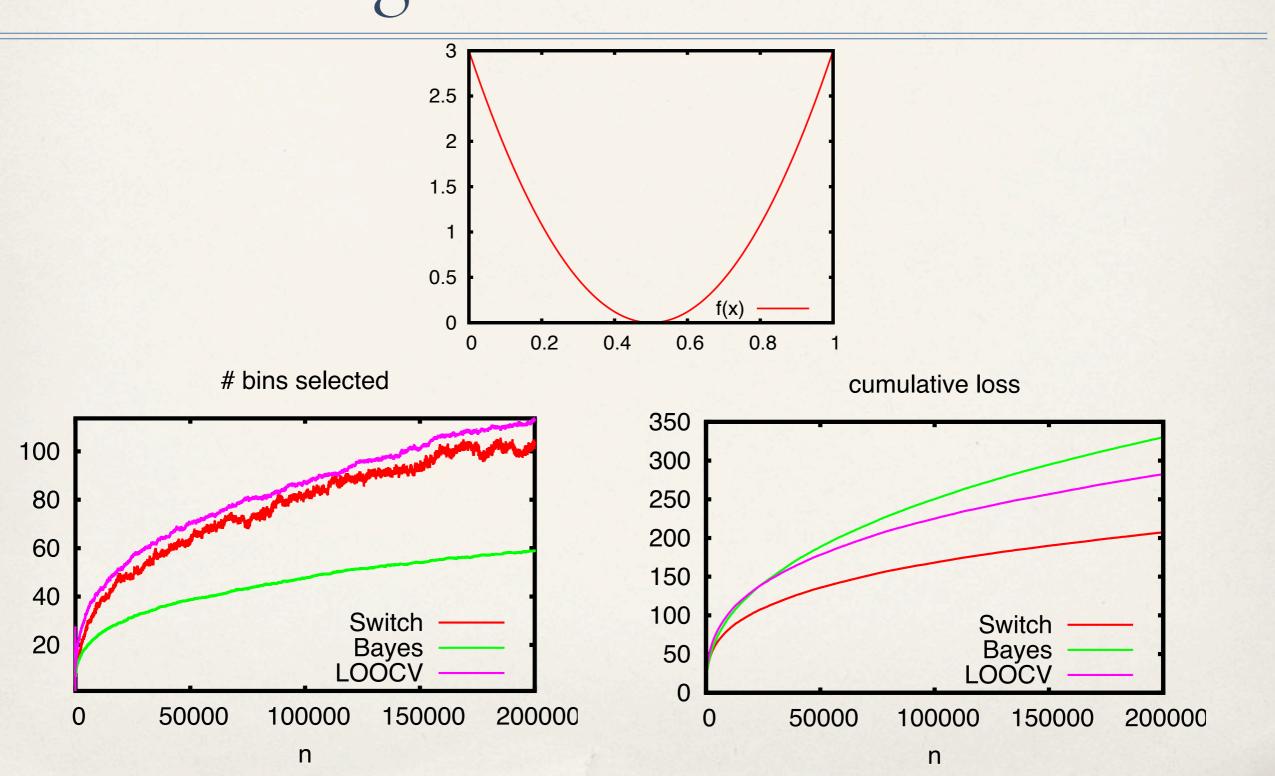


- * Pay less than $2\log(s+1) = 2\log(50001) \approx 32$ bits for not knowing s
- * Gain more than 20 000 bits by switching
- * Almost as good as knowing in advance when to switch!

Switch Distribution is Consistent for Histograms



Switch Distribution Predicts Well with Histograms



Theorem: Switching is Consistent

- Let $\mathcal{M}_1, \mathcal{M}_2, \ldots$ be models with priors w_1, w_2, \ldots on parameter sets $\Theta_1, \Theta_2, \ldots$ and marginal likelihoods $\bar{p}_1, \bar{p}_2, \ldots$
- * Suppose $\bar{p}_1, \bar{p}_2, \ldots$ are asymptotically sufficiently distinguishable in a suitable sense.
 - * For example, it is sufficient if the models consist of i.i.d. or Markov distributions, the parameter sets $\Theta_1, \Theta_2, \ldots$ are of different dimensionality and the priors have a density w.r.t. Lebesgue measure.
- * Then, for all k^* and all $p^* \in \mathcal{M}_{k^*}$, except for a subset of \mathcal{M}_{k^*} with prior w_{k^*} -probability 0, the switch distribution is **consistent** in that

$$\lim_{n \to \infty} p_{\text{sw}}(\mathcal{M}_{k^*} \mid X^n) = 1$$

with p^* -probability 1.

Setting for Prediction

- * Let $\mathcal{M}_1, \mathcal{M}_2, \ldots$ be i.i.d. models that can approximate a large set of i.i.d. distributions \mathcal{M}^* arbitrarily well (in Kullback-Leibler divergence)
- * For example, \mathcal{M}^* may be the set of all densities on [0,1] with bounded derivatives and $\mathcal{M}_1, \mathcal{M}_2, \ldots$ may be histograms
- * Suppose data $X^n = (X_1, \dots, X_n)$ are i.i.d. with distribution $p^* \in \mathcal{M}^*$

Risk

- * Let $p_{X^{n-1}}$ be the prediction of outcome X_n for some estimator p
 - * For example, p may be based on the Bayesian marginal likelihood
- * The risk is the expected divergence of the predictions of p from p*:

$$r_n(p^*,p) := \mathbf{E}_{X^{n-1} \sim p^*} D(p^* || p_{X^{n-1}})$$

• We take D to be the Kullback-Leibler divergence:

$$D(p^* || p_{X^{n-1}}) = \mathbf{E}_{X_n \sim p^*} [loss(p_{X^{n-1}}, X_n) - loss(p^*, X_n)]$$

Cumulative Risk

The cumulative risk is

$$R_n(p^*, p) = \sum_{i=1}^n r_i(p^*, p) = \mathbf{E}_{X^n} \left[\sum_{i=1}^n loss(p_{X^{i-1}}, X_i) - \sum_{i=1}^n loss(p^*, X_i) \right]$$

Motivation:

- Appropriate when the goal is sequential prediction
- Can convert to ordinary risk via online-to-batch conversion [Yang, Barron, '99]
- Equals redundancy in universal coding
- Avoids Yang's impossibility results

Theorem: Switching Achieves Minimax Cumulative Rate

- * Let $\bar{p}_1, \bar{p}_2, \ldots$ be estimators for the models $\mathcal{M}_1, \mathcal{M}_2, \ldots$ An oracle chooses model $k^{\circ} \equiv k^{\circ}(p^*, X^n)$, knowing the true distribution and the data.
- Suppose the cumulative risk of the oracle grows fast enough that

$$\frac{(\log n)^{2+\alpha}}{\sup_{p^* \in \mathcal{M}^*} R_n(p^*, \bar{p}_{k^\circ})} \to 0$$

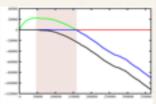
for some $\alpha > 0$ and the effective number of models is polynomial in n, i.e. $k^{\circ}(p^*, X^n) \leq n^{\beta}$ for some beta > 0.

* Then the switch distribution, with suitable prior π , predicts at least as well as the oracle:

$$\limsup_{n\to\infty} \frac{\sup_{p^*\in\mathcal{M}^*} R_n(p^*, p_{\text{sw}})}{\sup_{p^*\in\mathcal{M}^*} R_n(p^*, \bar{p}_{k^\circ})} \le 1.$$

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Conclusion

- Bayes and other BIC-like methods select the model that minimizes cumulative prediction error.
- * If the best-predicting model depends on the sample size, then they suffer from the catch-up phenomenon.
- * This explains the **AIC-BIC dilemma**.
- * The switch-distribution provably resolves the catch-up phenomenon:

	Consistent	Optimal rate of convergence
BIC, Bayes, MDL	Yes	No
AIC, LOO Cross-validation	No	Yes
Switch distribution	Yes	Yes (for cumulative risk)

References

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* If k is unknown, Bayesian model averaging also puts a prior π on k:

$$p(x_{n+1}|x^n) = \sum_{k} \bar{p}_k(x_{n+1}|x^n)\pi(k|x^n)$$