

UvA, February 15, 2013

An Introduction to Online Learning for Bayesians

Tim van Erven

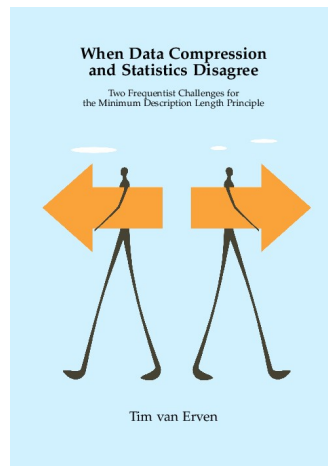


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Online Learning

- Decision problem
- Model: repeated game against an **adversary**
- Applications:
 - spam detection
 - data compression
 - online convex optimization
 - predicting electricity consumption
 - predicting air pollution levels
 - ...

Outline

- Online Learning
 - Introduction
 - Classification example
 - What can we achieve?
- Bayesian Methods

Repeated Game (Informally)

- Sequentially predict outcomes x_1, x_2, \dots
- Measure quality of prediction a_t by loss $\ell(x_t, a_t)$
- Before predicting x_t , get predictions (=advice) from K experts
- Goal: to predict as well as the best expert over T rounds.
- Data and Advice can be adversarial

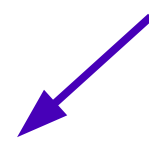
Repeated Game

- Every round $t = 1, 2, \dots$:
 1. Get expert predictions a_t^k ($k = 1, \dots, K$)
 2. Predict a_t^*
 3. Outcome x_t is revealed
 4. Measure nonnegative losses $\ell(x_t, a_t^*), \ell(x_t, a_t^k)$
- Goal: minimize *regret*

$$\sum_{t=1}^T \ell(x_t, a_t^*) - \min_k \sum_{t=1}^T \ell(x_t, a_t^k)$$

Repeated Game

- Every round $t = 1, 2, \dots$:
 1. Get expert predictions a_t^k ($k = 1, \dots, K$)
 2. Predict a_t^*
 3. Outcome x_t is revealed
 4. Measure nonnegative losses $\ell(x_t, a_t^*), \ell(x_t, a_t^k)$
- Goal: minimize *regret* Loss of the best expert

$$\sum_{t=1}^T \ell(x_t, a_t^*) - \min_k \sum_{t=1}^T \ell(x_t, a_t^k)$$


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Example: Spam Detection

Subject	From	
✉ Gratis Turkije. . .	Reizen Center	$x_1 = 1$
✉ uitnodiging hoorzitting reorganisatie FEW dinsdag 20 se...	Ivo van Stokkum	$x_2 = 0$
✉ Re: Urgent Business Inquiry.	Ubc Ltd	$x_3 = 1$
✉ Reminder: first colloquium	Jeu, R.M.H. de	$x_4 = 0$
✉ Informatie over VUnet	College van Bestuur	$x_5 = 0$
✉ USD 500 Free Deposit at PartyPoker!	PartyPoker	$x_6 = 1$
✉ YOU ARE A WINNER!!! VERY URGENT NOTIFICATION.	UK INTL. LOTTERY PROMOTION	$x_7 = 1$
✉ bachelor/master diploma uitreiking 14 september	Sotiriou, M.	$x_8 = 0$
✉ HAPPY NEW YEAR 2068	Anil Shilpakar	$x_9 = 1$
✉ Thailand Package	Anil Shilpakar	$x_{10} = 1$

Example: Spam Detection

- Labels: $x_t \in \{0, 1\}$
- Predictions: $a_t \in \{0, 1\}$
- 0/1-Loss: $\ell(x_t, a_t) = \begin{cases} 0 & \text{if } a_t = x_t \\ 1 & \text{if } a_t \neq x_t \end{cases}$
- Experts: K spam detection algorithms
- Regret: extra mistakes over best algorithm

$$\sum_{t=1}^T \ell(x_t, a_t^*) - \min_k \sum_{t=1}^T \ell(x_t, a_t^k)$$

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A First Algorithm

- Suppose one of the spam detectors is perfect
- Keep track of experts without mistakes so far:
 $S_t = \{k \mid \text{expert } k \text{ made no mistakes before round } t\}$
- Halving algorithm:
 $a_t^* = \text{majority vote among experts in } S_t$
- **Theorem:** $\text{regret} \leq \log_2 K$

A First Algorithm: Halving

Theorem: $\text{regret} \leq \log_2 K$

- Does not grow with T



Proof:

- Suppose halving makes m mistakes, $\text{regret} = m - 0$
- Every mistake eliminates at least half of S_t
- m is at most $\log_2 |S_1| = \log_2 K$ mistakes

No Assumptions?

- Consider two trivial spam detectors (experts):

$$a_t^1 = 0 \quad a_t^2 = 1$$

- I could be wrong all the time: $x_t \neq a_t^*$

Regret:

- Let n denote the number of ones in x_1, \dots, x_T
- Total loss best expert: $L := \min\{n, T - n\} \leq T/2$
- Linear** regret = $T - L \geq T/2$



Solution

- Labels: $x_t \in \{0, 1\}$
- Predict probability $a_t \in [0, 1]$ that $x_t = 1$
- Expected 0/1-loss = absolute loss:

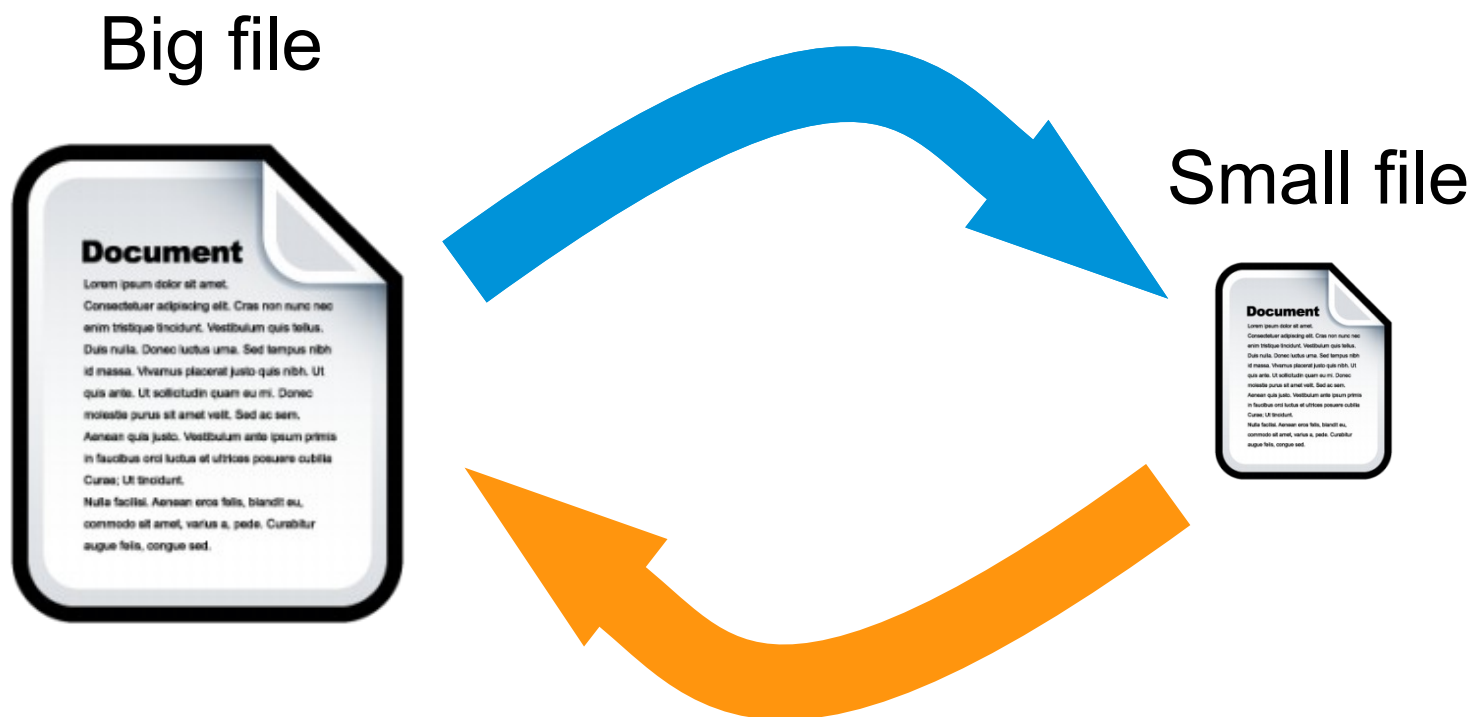
$$\ell(x_t, a_t) = |x_t - a_t|$$

- Achievable regret: $\sqrt{\frac{T}{2} \log K}$
- $O(\sqrt{T})$ is standard in online learning

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Example: Data Compression



- Experts: K data compression algorithms
- Regret: extra number of bits over best algorithm

Reduction to Online Learning

Data compression:

- x_1, \dots, x_T are characters in original big file
- Can encode x_t using $-\log P_t(x_t)$ bits, where P_t is a probability distribution I need to choose before seeing x_t

- Online learning:

- Predict distribution P_t for x_t
- **log loss:** $\ell(x_t, P_t) = -\log P_t(x_t)$

Can We Guess the Regret?

- K data compression algorithms
- For data compression I could use a two-part code
 1. $\log K$ bits identifies the best algorithm
 2. Concatenate with output of best algorithm
- Regret: $\log K$
- But in online learning I cannot split my output into two parts...

Bayes

- Experts define likelihoods:

$$P(x_t \mid x_{1:(t-1)}, k) := P_t^k(x_t)$$

- Prior π on unknown parameter $k \in \{1, \dots, K\}$

Bayes

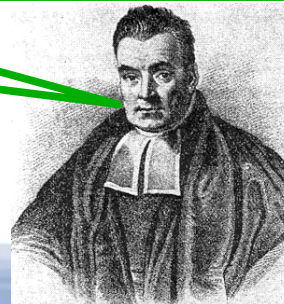
- Experts define likelihoods:

$$P(x_t \mid x_{1:(t-1)}, k) := P_t^k(x_t)$$

- Prior π on unknown parameter $k \in \{1, \dots, K\}$

$$P^*(x_t \mid x_{1:(t-1)}) = \sum_k P(x_t \mid x_{1:(t-1)}, k) \pi(k \mid x_{1:(t-1)})$$

where $\pi(k \mid x_{1:(t-1)}) \propto P(x_{1:(t-1)} \mid k) \pi(k)$ is the **posterior distribution** on experts



Bayesian Regret

- Mix expert predictions according to their posterior probability
- **Theorem:** If \hat{k} is the best expert, then the Bayesian regret for log loss is at most $-\log \pi(\hat{k})$
- For uniform prior $\pi(k) = 1/K$ this is $\log K$, as expected.
- This is optimal as $K, T \rightarrow \infty$

Bayesian Regret

Theorem: If \hat{k} is the best expert, then the Bayesian regret for log loss is at most $-\log \pi(\hat{k})$

Proof:

- Total loss: $\sum_{t=1}^T -\log P^*(x_t | x_{1:(t-1)}) = -\log P^*(x_{1:T})$
- Marginal likelihood $P^*(x_{1:T})$ is bounded by

$$P^*(x_{1:T}) = \sum_k P(x_{1:T} | k) \pi(k) \geq P(x_{1:T} | \hat{k}) \pi(\hat{k})$$

- Take negative logarithms
- Loss of best expert equals $-\log P(x_{1:T} | \hat{k})$

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How to Lie to Bayes



Log loss:

- **Likelihoods** $P(x_t | x_{1:(t-1)}, k) = P_t^k(x_t) = e^{-\ell_{\log}(x_t, P_t^k)}$
- **Loss is** $\ell_{\log}(x_t, P_t) = -\log P_t(x_t)$



How to Lie to Bayes



Log loss:

- Likelihoods $P(x_t | x_{1:(t-1)}, k) = P_t^k(x_t) = e^{-\ell_{\log}(x_t, P_t^k)}$
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General loss (“exponential weights”):

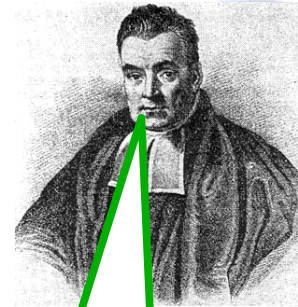
- Fix $\eta > 0$. Fake likelihoods

$$P(x_t \mid x_{1:(t-1)}, k) = e^{-\eta \ell(x_t, a_t^k)}$$

- Log loss equals $-\log P(x_t | x_{1:(t-1)}, k) = \eta \ell(x_t, a_t^k)$



How to Lie to Bayes



Log loss:

- Likelihoods $P(x_t | x_{1:(t-1)}, k) = P_t^k(x_t) = e^{-\ell_{\log}(x_t, P_t^k)}$
- Loss is $\ell_{\log}(x_t, P_t) = -\log P_t(x_t)$

These are not probabilities!

General loss (“exponential”)

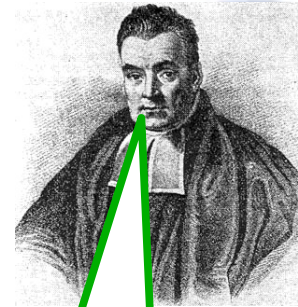
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How to Lie to Bayes



Log loss:

- Likelihoods $P(x_t | x_{1:(t-1)}, k) = P_t^k(x_t) = e^{-\ell_{\log}(x_t, P_t^k)}$
- Log loss $\ell_{\log}(x_t, P_t) = -\log P_t(x_t)$

But their values are in $[0, 1]$,
so you cannot see that!

These are not
probabilities!

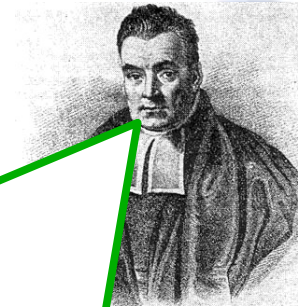
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Mixability

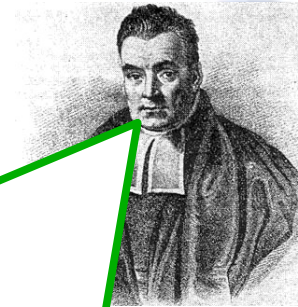


If the loss is not **log loss** and predictions are not **probabilities**, then you cannot predict with the **posterior distribution**

$$P^*(x_t|x_{1:(t-1)}) = \sum_k P(x_t|x_{1:(t-1)}, k)\pi(k|x_{1:(t-1)})$$



Mixability



If the loss is not **log loss** and predictions are not **probabilities**, then you cannot predict with the **posterior distribution**

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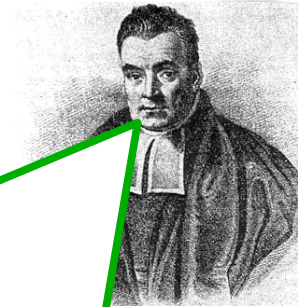
I only need **mixability**...

A loss is η -mixable if, for any posterior distribution, we can find a prediction a^* that is at least as good:

$$e^{-\eta\ell(x_t, a^*)} \geq P^*(x_t|x_{1:(t-1)}) \quad \text{for any } x_t$$



Mixability



If the loss is not **log loss** and predictions are not **probabilities**, then you cannot predict with the **posterior distribution**

$$P^*(x_t|x_{1:(t-1)}) = \sum_k P(x_t|x_{1:(t-1)}, k)\pi(k|x_{1:(t-1)})$$

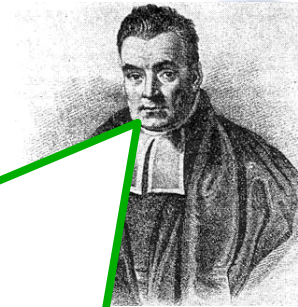
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Mixability



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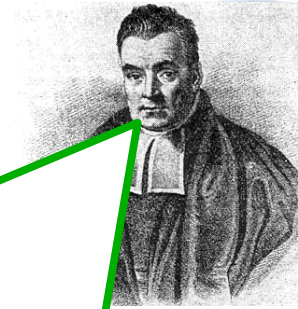
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Mixability



If the loss is not **log loss** and predictions are not **probabilities**, then you cannot predict with the **posterior distribution**

$$P^*(x_t|x_{1:(t-1)}) = \sum_k P(x_t|x_{1:(t-1)}, k)\pi(k|x_{1:(t-1)})$$

I only need **mixability**...

A loss is η -mixable if, for any **distribution** $w(a)$, we can find a prediction a^* that is at least as good:

$$e^{-\eta\ell(x, a^*)} \geq \sum_a e^{-\eta\ell(x, a)} w(a) \quad \text{for any } x$$

Mixable Losses

- Regret bounded by $\frac{-\log \pi(\hat{k})}{\eta}$
- For largest possible η this is optimal as $K, T \rightarrow \infty$

Examples:

- Square loss is 2-mixable:

$$\ell(x_t, a_t) = (x_t - a_t)^2 \quad x_t, a_t \in [0, 1]$$

- Relative entropy loss is 1-mixable:

$$\ell(x_t, a_t) = x_t \log \frac{x_t}{a_t} + (1 - x_t) \log \frac{1 - x_t}{1 - a_t} \quad x_t, a_t \in [0, 1]$$

- Absolute loss is **not** η -mixable for any $\eta > 0$

Mixable losses

Theorem 1: The Bayesian regret for log loss is at most $-\log \pi(\hat{k})$

Theorem 2: The Bayesian regret for any η -mixable loss is at most $\frac{-\log \pi(\hat{k})}{\eta}$

Proof by reduction to log loss:

$$\begin{aligned} \sum_{t=1}^T \eta \ell(x_t, a_t^*) - \min_k \sum_{t=1}^T \eta \ell(x_t, a_t^{\hat{k}}) &\leq \\ \sum_{t=1}^T \ell_{\log}(x_t, P(\cdot | a_t^*)) - \min_k \sum_{t=1}^T \ell_{\log}(x_t, P_t(\cdot | a_t^{\hat{k}})) &\leq -\log \pi(\hat{k}) \end{aligned}$$

$\text{I} \wedge$ II

Log Loss is Special

- Reduction to log loss suggests that:

“All mixable losses are like log loss in some way”

- New characterization of mixable losses captures in which way. [vE, Reid, Williamson, 2011]

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Absolute Loss

- Labels: $x_t \in \{0, 1\}$
- Predict probability $a_t \in [0, 1]$ that $x_t = 1$
- Expected 0/1-loss = absolute loss:

$$\ell(x_t, a_t) = |x_t - a_t|$$

Absolute Loss

- Labels: $x_t \in \{0, 1\}$
- Predict probability $a_t \in [0, 1]$ that $x_t = 1$
- Expected 0/1-loss = absolute loss:

$$\ell(x_t, a_t) = |x_t - a_t|$$

- Not mixable...
- But can be approximated by an η -mixable loss up to approximation error $\frac{\eta}{8}$ per round!

Bayes for Absolute Loss

Theorem: Bayes for absolute loss with $\eta = \sqrt{\frac{8 \log K}{T}}$ has regret at most $\sqrt{\frac{T}{2} \log K}$

Proof:

- If loss were mixable, the regret would be bounded by $\frac{\log K}{\eta}$
- Approximation error: $\eta/8$ per round
- Resulting bound: $\frac{\log K}{\eta} + \frac{\eta T}{8}$

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Converging Posterior

- Approximation error $\frac{\eta}{8}$ does not depend on the posterior distribution
- If the posterior distribution converges we can do better...

Converging Posterior

- Approximation error $\frac{\eta}{8}$ does not depend on the posterior distribution
- If the posterior distribution converges we can do better...

Lemma: For $\eta \leq 1$ the approximation error is bounded by

$$(e - 2)\eta(1 - \pi(k \mid x_{1:(t-1)}))$$

for any k [vE, Grünwald, Koolen, De Rooij, 2011]

Converging Posterior

- Can choose η such that the regret is bounded by:

1. If the posterior converges sufficiently fast:

$$O(K)$$

2. Always, even if the posterior does not converge:

$$O(\sqrt{T \log K})$$

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Summary

- Online Learning
 - Repeated prediction game
 - Examples: data compression, classification
 - Want sublinear regret: constant or $O(\sqrt{T})$
- Bayesian Methods
 - Generalization to mixable losses
 - Generalization to classification
 - Better classification when posterior converges quickly

Online Learning

Prediction with Expert Advice:

- Finite/countable number of experts

Online Convex Optimization:

- Learn convex combinations of experts

Online Learning

Prediction with Expert Advice:

- Finite/countable number of experts

Gradient trick:
replace a convex
loss by a linear
approximation

Online Convex Optimization:

- Learn convex combinations of experts

References

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