# **Machine Learning 2007: Lecture 13**

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December 12, 2007

# **Overview**

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# **Organisational Matters**

# Organisational Matters

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### **Enrolling for the final exam:**

Someone reported getting an error when enrolling for the final exam on TISVu. Anyone else having troubles?

### **Today's Overview:**

- I will ask things on the exam that are not in today's overview.
- The overview is only intended to give you a high-level view of the course, which should help you organise all the information.
- A few additional explanations of things that I think may have been unclear. For example, (the role of) random variables.

### **MDL** lecture:

Peter did his lecture on the blackboard, so there are no slides.

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### **MDL** lecture:

- Peter did his lecture on the blackboard, so there are no slides.
- To help you study, I will make slides myself.
- These will be ready before Saturday evening.

# **Overview**

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# Machine Learning Categories

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**Prediction:** Given data  $D = y_1, \dots, y_n$ , predict how the sequence continues with  $y_{n+1}$ .

**Regression:** Given data  $D = \begin{pmatrix} y_1 \\ \mathbf{x}_1 \end{pmatrix}, \dots, \begin{pmatrix} y_n \\ \mathbf{x}_n \end{pmatrix}$ , learn to predict

the value of the label y for any new feature vector  $\mathbf{x}$ . Typically y can take infinitely many values. Acceptable if your prediction is close to the correct y.

**Classification:** Given data  $D = \begin{pmatrix} y_1 \\ \mathbf{x}_1 \end{pmatrix}, \dots, \begin{pmatrix} y_n \\ \mathbf{x}_n \end{pmatrix}$ , learn to predict the class label y for any new feature vector  $\mathbf{x}$ . Only finitely many categories. Your prediction is either correct or wrong.

Not all machine learning problems fit into these categories.

# Hypothesis Spaces and Models

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- Hypothesis h: candidate description of regularity in the data
- Hypothesis space  $\mathcal{H}$ : set of hypotheses being considered
- Model  $\mathcal{M}$ : Hypothesis space that contains only probabilistic hypotheses

### **Example:**

Suppose we use the following hypothesis space with deterministic hypotheses for prediction of binary outcomes  $y_1, y_2, \ldots$ 

$$h_1$$
:  $y_n = 0$   
 $\mathcal{H} = \{h_1, h_2\}$   $h_2$ :  $y_n = 1$ 

If our hypotheses are not so sure about what is going to happen, then we should use probabilistic hypotheses:

$$\mathcal{M} = \{P_1, P_2\}$$
  $P_1$ :  $P_1(y_n = 1) = 0.3$   
 $P_2$ :  $P_2(y_n = 1) = 0.8$ 

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# Least squares regression

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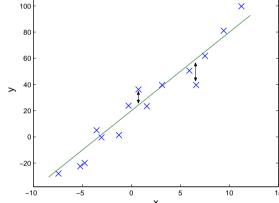
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- Method for regression
- Selects the hypothesis from  ${\cal H}$  that minimizes the sum of squared errors on the data.
- Relies on representation bias to generalise.

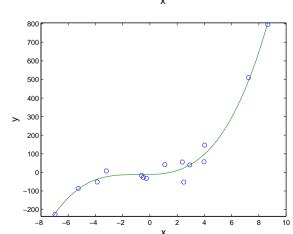
# **Linear regression:**

- For d-dimensional x
- $\mathcal{H} = \{ w_0 + w_1 x_1 + \ldots + w_d x_d \mid \mathbf{w} \in \mathbb{R}^{d+1} \}$
- In example d=1.



# Polynomial regression with *k*-degree polynomials:

- For 1-dimensional x
- $\bullet \mathcal{H} = \{w_0 + w_1 x_1 + w_2 x_1^2 + \dots w_d x_1^k | \mathbf{w} \in \mathbb{R}^{k+1} \}$
- In example k = 3.



# LIST-THEN-ELIMINATE algorithm

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### **Method:**

- Method for classification/concept learning (e.g. for EnjoySport data)
- Finds the set, VersionSpace, of hypotheses in  $\mathcal{H}$  that are consistent with the training data.
- Can classify a new instance x if all hypotheses in VersionSpace agree on its classification.

### Inductive bias:

- Relies on representation bias to generalise:
- With  $\mathcal{H}$  containing a list of constraints on attributes, it has a strong representation bias.
- With H containing all possible hypotheses it cannot generalise: bias is unavoidable!

# The Perceptron

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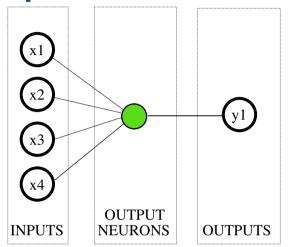
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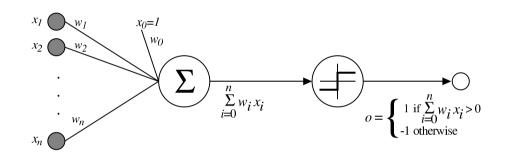
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### **Simple Neural Network:**



# Mitchell's Drawing:



**Equation:** 

$$h_{\mathbf{w}}(\mathbf{x}) = \begin{cases} 1 & \text{if } w_0 + w_1 x_1 + \dots w_d x_d > 0, \\ -1 & \text{otherwise.} \end{cases}$$

# The Perceptron

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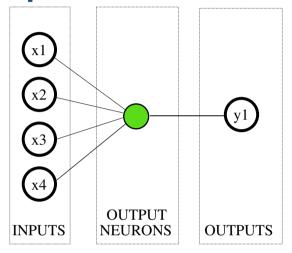
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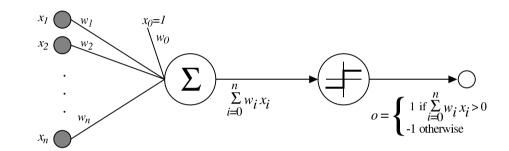
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### **Simple Neural Network:**



### Mitchell's Drawing:



$$h_{\mathbf{w}}(\mathbf{x}) = \begin{cases} 1 & \text{if } w_0 + w_1 x_1 + \dots w_d x_d > 0, \\ -1 & \text{otherwise.} \end{cases}$$

- A perceptron does classification.
- It is a linear function with a threshold.
- Can learn functions with a linear decision boundary, but there are some functions that it can never represent (e.g. xor).

# **Gradient Descent**

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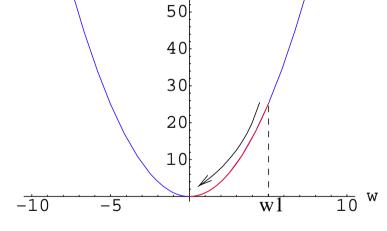
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- Gradient descent is a method to find the minimum of a function:  $\min_{\mathbf{w}} f(\mathbf{w})$ .
- It works for convex functions and also some other functions, but not for functions that have local minima.
- It can be used, for example, to find the weights that minimize the error in least squares regression.

### **General Idea:**

- 1. Pick some starting point  $w_1$ .
- 2. Keep taking small steps downhill:  $f(w_1) > f(w_2) > f(w_3) > \dots$
- 3. The negative derivative -f'(w) points the way. (The gradient generalises the derivative in case w has dimension  $\geq 2$ .)
- 4. Stop at the minimum. (Here f'(w) = 0.)



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- Given train set D, k-nearest neighbour classifies a new vector  $\mathbf{x}$  by voting among the k examples in D that are closest to  $\mathbf{x}$ .
- Distance is the essential ingredient.

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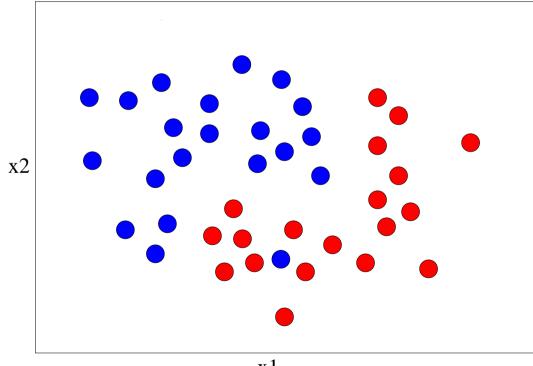
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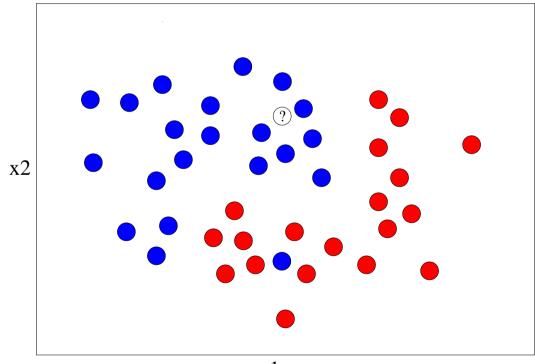
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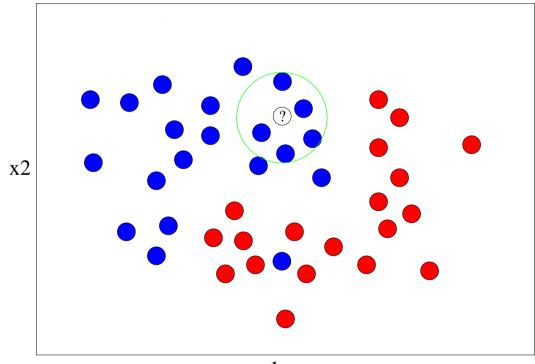
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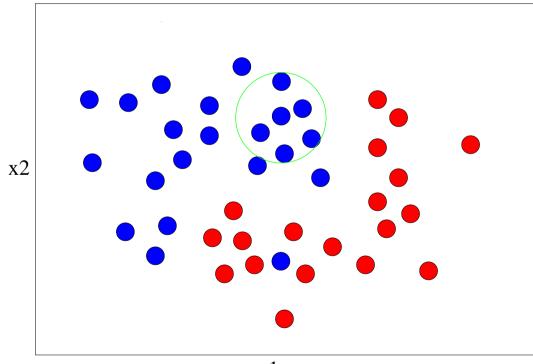
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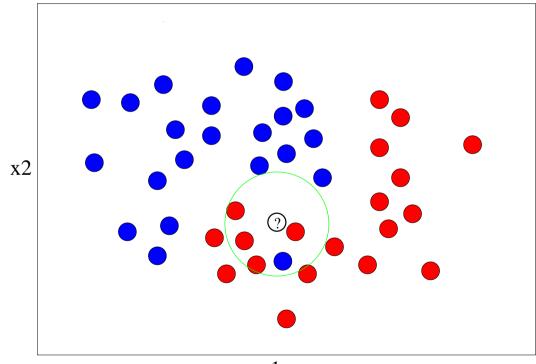
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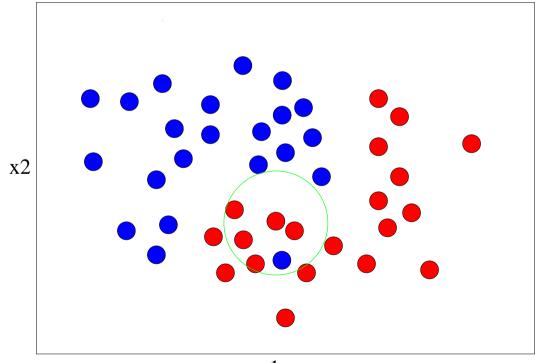
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# The ID3 Algorithm

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- Does classification by learning a decision tree from data.
- Decision trees can only handle attributes with a finite number of values.

### Main ideas:

- 1. Start by selecting a root attribute for the tree.
- Then construct the tree recursively by adding more and more attributes to it.
- 3. Attributes are chosen greedily based on their estimated mutual information with the class labels (information gain).
- 4. Stop growing the tree when it is consistent with all the data.

# The ID3 Algorithm

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### Inductive bias:

- No representation bias
- Preference bias: prefers shorter trees with attributes that have a higher information gain closer to the root.
- After running ID3, post-pruning reduces overfitting.

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# Train, Test and Validation Sets

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- Train set: data  $D_{\text{train}}$  used to train a machine learning algorithm (e.g. to select a hypothesis h)
- Validation set: used to estimate parameters.
- **Test set:** data  $D_{\text{test}}$  used to evaluate the performance of the algorithm (e.g. by evaluating  $\text{Error}(h, D_{\text{test}})$ )

# Overfitting: One of the Main Problems in ML

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**Student Discussion** 

**Definition:** A hypothesis  $h \in \mathcal{H}$  overfits the train set if there exists a hypothesis  $h' \in \mathcal{H}$  such that: h performs better than h' on the **train set**:

$$\mathsf{Error}(h, D_{\mathsf{train}}) < \mathsf{Error}(h', D_{\mathsf{train}}),$$
 (1)

but h generalises less well than h': For a sufficiently large **test set**,

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 (2)

**Example in prediction:** If many students predict the outcome of a throw with a die, some will predict correctly, even though they have no special insight. They will not predict better than the others if we throw the die again.

**Reason for overfitting:** When selecting hypotheses (students) from a **large hypothesis space** (class), some will fit the train set well by coincidence.

# Overfitting with ID3:

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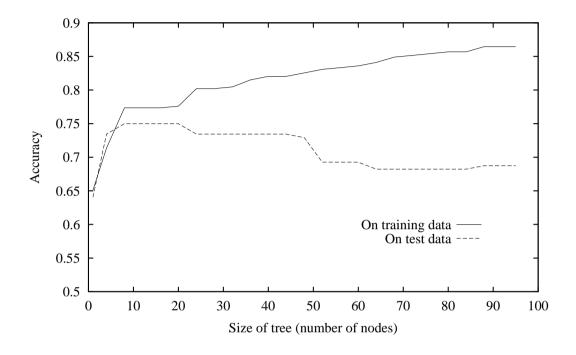
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# Overfitting in Least Squares with Polynomials::

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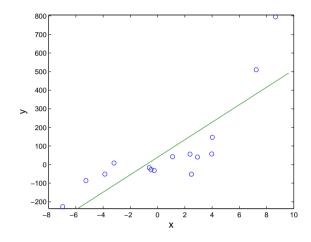
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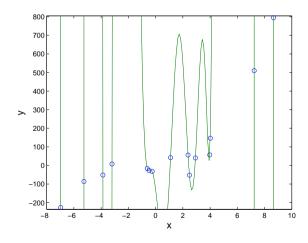
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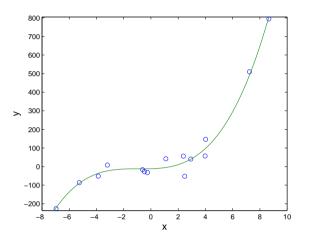
**Student Discussion** 



Linear Function (Simple)



14th Degree polynomial (Complex)



Third Degree Polynomial (Intermediate)

# Minimum Description Length Learning

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### MDL is a theory of learning based on the ideas:

- Learning is looking for structure/regularity in data.
- All regularity can be used to compress the data.

### **Properties:**

- Automatic protection against overfitting:
- We need many bits to describe a "complex" hypothesis.

### **Examples:**

- Grammar learning
- Regression with polynomials

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# **Probability Distributions**

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To precisely define a probability distribution (e.g. a probabilistic hypothesis) P we need to specify:

- 1. Sample space  $\Omega$ : Which outcomes are possible. E.g.  $\Omega = \{a, b, c\}$ .
- 2. Mass function p: What is the probability mass of each of the individual outcomes? E.g. p(a) = 1/6, p(b) = 1/2, p(c) = 1/3.
- 3. The masses may not be negative and have to sum up to 1.

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- 3. The masses may not be negative and have to sum up to 1.

Now what is the probability that we will either get an a or a c?

- Event A: More abstractly, what is the probability that we will observe an outcome in the set  $A = \{a, c\}$ ?
- Any set of possible outcomes is an event, even the empty set or the set containing all outcomes. Hence  $A \subseteq \Omega$ .
- Probability distribution:  $P(\{a,c\}) = p(a) + p(c) = 1/2$ .
- In general, for any event A:  $P(A) = \sum_{\omega \in A} p(\omega)$ .

# **Conditional Probability**

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• Given that we will get an outcome in event B, what is the probability that the outcome is also in event A?

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- Given that we will get an outcome in event B, what is the probability that the outcome is also in event A?
- For any two events  $A, B \subseteq \Omega$  the conditional probability  $P(A \mid B)$  of A given B is defined as:

$$P(A \mid B) = \frac{P(A \cap B)}{P(B)}$$

**Example:**  $P(\{a,d\} \mid \{a,c\}) = \frac{P(\{a\})}{P(\{a,c\})}$ 

# **Conditional Probability**

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# Bayes' rule:

- $P(A \mid B) = \frac{P(B|A)P(A)}{P(B)}$
- Bayes' rule is often useful when we want to compute  $P(A \mid B)$ , but only know  $P(B \mid A)$
- (and P(A) and P(B), which are often easier because they only concern a single event).

# Independent Events

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### **Independent Events:**

- Two events A and B are independent if the probability of one of them doesn't change when we condition on the other:  $P(A \mid B) = P(A)$ .
- Or equivalently:  $P(A \cap B) = P(A)P(B)$

### **Conditional Independence:**

• Two events A and B are conditionally independent given event C if  $P(A \cap B \mid C) = P(A \mid C)P(B \mid C)$ .

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# Naive Bayes:

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### Classification:

- Naive Bayes is a method for classification.
- It assumes that the outcomes  $(y, \mathbf{x})^{\top}$  that we get are distributed according to some unknown distribution P.
- To classify  $\mathbf{x}$  it selects the y with highest conditional probability:  $\arg\max_y P(Y=y\mid X=\mathbf{x})$ .

# Estimating P:

- To maximize  $P(Y = y \mid X = \mathbf{x})$  it applies Bayes' rule.
- And it assumes that the attributes of x are conditionally independent given the class label y.
- Then it estimates the required probabilities from the training data.

# Random Variables:

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What does the expression  $P(Y = y' \mid X = \mathbf{x}')$  mean?

- Here Y and X are random variables.
- Y = y' defines the event "all possible pairs  $(y, \mathbf{x})^{\top}$  such that y = y'"
- $X = \mathbf{x}'$  defines the event "all possible pairs  $(y, \mathbf{x})^{\top}$  such that  $\mathbf{x} = \mathbf{x}'$ "

# **Example:**

- Suppose y can take the possible values 0 and 1.
- And x can take the possible values 10, 20, 30.
- Then Y = 0 defines the event  $\{(0, 10)^{\top}, (0, 20)^{\top}, (0, 30)^{\top}\}.$
- And X = 30 defines the event  $\{(0,30)^{\top}, (1,30)^{\top}\}$ .
- If x is, say, 2-dimensional, then we might have separate random variables  $X_1$  and  $X_2$  to talk about the values of  $x_1$  and  $x_2$ .

# Maximum Likelihood Parameter Estimation

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# **Training data and model:**

$$D = \begin{bmatrix} y_1 & y_2 & y_3 & y_4 & y_5 & y_6 & y_7 & y_8 \\ 0 & 1 & 1 & 1 & 0 & 1 & 1 & 1 \end{bmatrix}$$

$$\mathcal{M} = \left\{ P_{\theta} \mid \theta \in \left\{ \frac{1}{4}, \frac{1}{2}, \frac{3}{4} \right\} \right\} \quad \text{where } P_{\theta}(y_n = 1) = \theta.$$

### Likelihood:

$\theta$	1/4	1/2	3/4
$P_{\theta}(D)$	$(1/4)^6(3/4)^2$	$(1/2)^8$	$(3/4)^6(1/4)^2$
	= 9/65536	=256/65536	=729/65536

### **Maximum Likelihood Parameter Estimation:**

$$\hat{\theta} = \arg\max_{\theta} P_{\theta}(D) = 3/4$$

# Bayesian Learning

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- Given some model with parameter  $\theta$ , construct a **single** distribution  $P_{\text{Baves}}$  on both data D and the parameter  $\theta$ .
- We have to introduce a prior  $\pi(\theta)$ , which determines the relative importance of each  $\theta$ .
- Now we can compute the
  - posterior distribution over parameters given the training data:  $\pi(\theta = 3/4 \mid D)$ ;
  - find the MAP hypothesis:  $\theta_{MAP} = \arg \max_{\theta} \pi(\theta \mid D)$
  - predictive distribution over the next outcome given the training data:

$$P_{\text{Bayes}}(y_{n+1} = 1 \mid D) = \sum_{\theta} P_{\theta}(y_{n+1}) \pi(\theta \mid D)$$
.

### **Remarks:**

- Automatically protects against overfitting.
- Widely used (much better known than MDL).

# Implications of Machine Learning

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- Price of car/health insurance made dependent on the learned probability of getting an accident/getting ill, based on your genes.
- Learning a persons preferences from search queries to improve search results. I am sure that Google can find out:
  - your personal interests
  - your (lack of) religion
  - your sexual preferences
  - your (controversial?) political views
- Learning racist characteristics. How do you know that your learning method is racist? It may very subtly be using features that are correlated to race.
- Ability to get a job with the government dependent on fit to the profile of a terrorist. Think about overfitting like in the dice prediction game.

# References

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